

CHAPTER III

THE EQUIVALENCE BETWEEN THE CATEGORY C OF CROSSED MODULES AND THE CATEGORY DA' OF SPECIAL DOUBLE ALGEBROIDS WITH CONNECTIONS

0. INTRODUCTION:

R. Brown and C.B. Spencer [B-S-1] have defined a functor (crossed modules over groups) \rightarrow (double groupoids), and they showed that this gives an equivalence between the category of crossed modules over groups and the category of special double groupoids with special connections and one vertex. The structure of connection on a double groupoid was shown in [B-H-1] to be equivalent to a structure of thin squares, and a convenient notation for thin squares was later developed and exploited by R. Brown [Br-2]. Also [S-1] proved an equivalence between 2-categories and double categories with connections. Thin structures on double categories were exploited in [S-W-1]. Finally, it was proved in [B-H-2] that crossed modules over groupoids are equivalent to double groupoids with connections; indeed this is a special case of an equivalence between crossed complexes (over groupoids) and ω -groupoids.

Our programme is to prove results parallel to the above in the context of algebroids rather than groupoids; that is we would like to prove that there exist an equivalence between ω -algebroids and crossed complexes (over algebroids).

Rather than move to the general case immediately , we give in this chapter the case $n = 2$, that is , for double algebroid . This will familiarise the reader with the techniques involved . Also some of our lemmas for $n = 2$ will be applied the general case , and the complications of their proof makes it easier to give the case $n = 2$ when the notation is simpler than in general .

As explained in the Introduction , in this thesis we do not acheive the general result , but we do obtain a lot of information on the general situation and complete results for $n = 2,3,4$.

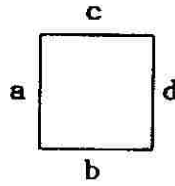
1. THIN STRUCTURES AND CONNECTIONS:

We will use the example which was given in chapter 2 § 3 in order to define the extra structure needed later (we should mention that the example of $\square B$ given before is analogous to the example of double category due to Ehresmann [Eh-1]) . But before that we start to define a special double algebroid .

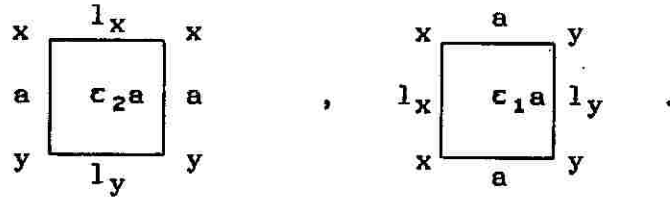
Definition 3.1.1: Let D be a double R -algebroid . We say that D is a special double R -algebroid if $D_1 = D_2$.

Referring to the definition (2.1.9) , a morphism (ψ_0, ψ_1, ψ_2) of double algebroids such that $\psi_1 = \psi_2$ is called a morphism of special double algebroids .

Suppose given a special double algebroid D . Then there will be squares of D with commuting boundary , that is , with edges given by



and for which $ab = cd$. Examples of such squares are degenerate squares ;



Among the others there seems no way to distinguish any one from another . We therefore impose on D an additional structure of "thin" squares .

Definition 3.1.2: Let D be a special double algebraoid . A thin structure on D is a morphism $\theta : \square D_1 \dashrightarrow D$ of special double algebraoids such that θ is the identity on D_1 . Hence

$$\theta \left(\begin{array}{cc} a & c \\ & d \\ b & \end{array} \right) = \left(\begin{array}{cc} a & c \\ & d \\ b & \end{array} \right) . \text{ An element } \theta \left(\begin{array}{cc} a & c \\ & d \\ b & \end{array} \right) \text{ is called } \underline{\text{thin}} , \text{ and}$$

is often written simply $\left(\begin{array}{cc} a & c \\ & d \\ b & \end{array} \right)$, when θ is clear from the context .

Remark 3.1.3: Because θ is a morphism any composite of thin squares is thin ; any sum of thin squares is thin ; any scalar multiple of a thin square is thin . Thin squares should be thought of as generalisations of identity elements $\epsilon_1 a$, $\epsilon_2 a$ in a special double algebraoid .

Instead of thin structures , one can use an alternative further structure on D , namely a connection (Γ , Γ') . This will be important later for generalisation to higher dimensions .

Definition 3.1.4: Let D be a special double algebroid . We define a connection on D to be a pair of functions

$\Gamma, \Gamma' : D_2 \rightarrow D$ such that

(3.1.4)(i) for any $a \in D_2(x,y)$, then Γa , $\Gamma'a$ have edges given by



(Clearly these two squares are commutative) .

We assume the following axioms: for all $a,b \in D_2$ such that ab is defined

$$\Gamma'a *_2 \Gamma a = c_1 a \quad (3.1.4)(ii)$$

$$\Gamma'a *_1 \Gamma a = c_2 a$$

$$\Gamma'(ab) = (\Gamma'a *_1 c_1 a) *_2 (c_2 a *_1 \Gamma'a) = \Gamma'a *_2 (c_2 a *_1 \Gamma'b) \quad (3.1.4)(iii)$$

$$\Gamma(ab) = (\Gamma a *_1 c_2 b) *_2 (c_1 b *_1 \Gamma b) = (\Gamma a *_1 c_2 b) *_2 \Gamma b$$

(3.1.4)(iv) Let $\alpha, \beta, \gamma \in D$ have boundaries given by

$$\underline{\partial}\alpha = \begin{pmatrix} c \\ a & d \\ b \end{pmatrix}, \quad \underline{\partial}\beta = \begin{pmatrix} c \\ a_1 & d_1 \\ b \end{pmatrix}, \quad \underline{\partial}\gamma = \begin{pmatrix} c_1 \\ a & d \\ b_1 \end{pmatrix};$$

then we have

$$\Gamma'(a+a_1) *_2 (\alpha +_1 \beta) *_2 \Gamma(d+d_1) = (\Gamma'a *_2 \alpha *_2 \Gamma d) +_2 (\Gamma'a_1 *_2 \beta *_2 \Gamma d_1) .$$

(3.1.4)(v) Let $r \in R$ and $\alpha \in D$ with boundary given by

$$\underline{\partial}\alpha = \begin{pmatrix} c \\ a & d \\ b \end{pmatrix}; \text{ then we have}$$

$$\Gamma'ra *_2 (r \cdot_1 \alpha) *_2 \Gamma rd = r \cdot_2 (\Gamma'a *_2 \alpha *_2 \Gamma d) .$$

These axioms make sense in terms of boundaries , as shown in the diagrams below :

let $a:x \rightarrow y$, $b:y \rightarrow z$ for $x,y,z \in D_0$; then the axiom (3.1.4)(ii) can be pictured as

$$\begin{array}{|c|c|c|} \hline x & l & x & a & y \\ \hline l & \Gamma'a & a & \Gamma a & l \\ \hline x & a & y & l & y \\ \hline \end{array} = \begin{array}{|c|c|} \hline x & a & y \\ \hline l & c_1 a & l \\ \hline x & a & y \\ \hline \end{array} ,$$

$$\begin{array}{|c|c|c|} \hline x & l & x \\ \hline l & \Gamma'a & a \\ \hline x & a & y \\ \hline a & \Gamma a & l \\ \hline y & l & y \\ \hline \end{array} = \begin{array}{|c|c|} \hline x & l & x \\ \hline a & c_2 a & a \\ \hline y & l & y \\ \hline \end{array} ,$$

The axiom (3.1.4)(iii) is pictured as ;

$$\begin{array}{|c|c|} \hline x & l & x \\ \hline l & \Gamma'ab & ab \\ \hline x & ab & z \\ \hline \end{array} = \begin{array}{|c|c|c|} \hline x & l & x & l & x \\ \hline l & \Gamma'a & a & c_2 a & a \\ \hline x & a & y & l & y \\ \hline l & c_1 a & l & \Gamma'b & b \\ \hline x & a & y & b & z \\ \hline \end{array} ,$$

$$\begin{array}{|c|c|} \hline x & ab & z \\ \hline ab & \Gamma ab & l \\ \hline z & l & z \\ \hline \end{array} = \begin{array}{|c|c|c|} \hline x & a & y & b & z \\ \hline a & \Gamma a & l & c_1 b & l \\ \hline y & l & y & b & z \\ \hline b & c_2 b & b & \Gamma b & l \\ \hline z & l & z & l & z \\ \hline \end{array} .$$

The axiom (3.1.4)(iv) , is pictured as

$$\begin{array}{|c|c|c|c|} \hline x & x & c & w & d+d_1 & z \\ \hline a+a_1 & \alpha+a_1\beta & d+d_1 & & & \\ \hline x & a+a_1 & y & b & z & z \\ \hline \end{array} = \begin{array}{|c|c|} \hline x & cd+cd_1 & z \\ \hline x & ab+a_1b & z \\ \hline \end{array} = \begin{array}{|c|c|} \hline x & cd & z \\ \hline x & ab & z \\ \hline \end{array} +_2 \begin{array}{|c|c|} \hline x & cd_1 & z \\ \hline x & a_1b & z \\ \hline \end{array} =$$

$$\begin{array}{|c|c|c|c|} \hline x & x & c & w & d & z \\ \hline a & \alpha & d & & & \\ \hline x & a & y & b & z & z \\ \hline \end{array} +_2 \begin{array}{|c|c|c|c|} \hline x & x & c & w & d_1 & z \\ \hline a_1 & \beta & d_1 & & & \\ \hline x & a_1 & y & b & z & z \\ \hline \end{array} ,$$

The axiom (3.1.4)(v) , is pictured as ;

the left hand side is ;

$$\begin{array}{ccc}
 \begin{array}{|c|c|c|c|}
 \hline
 x & x & w & z \\
 \hline
 \text{ra} & r \cdot 1 & \alpha & rd \\
 \hline
 x & y & z & z \\
 \hline
 \text{ra} & b & & \\
 \hline
 \end{array} & = & \begin{array}{|c|c|}
 \hline
 x & z \\
 \hline
 \text{rcd} & \\
 \hline
 x & z \\
 \hline
 \text{rab} & \\
 \hline
 \end{array}
 \end{array}$$

The other side is ;

$$\begin{array}{ccc}
 \begin{array}{|c|c|c|c|}
 \hline
 x & x & w & z \\
 \hline
 a & & d & \\
 \hline
 x & y & z & z \\
 \hline
 a & b & & \\
 \hline
 \end{array} & = r \cdot 2 & \begin{array}{|c|c|}
 \hline
 x & z \\
 \hline
 cd & \\
 \hline
 x & z \\
 \hline
 ab & \\
 \hline
 \end{array}
 \end{array}$$

$$= \begin{array}{|c|c|}
 \hline
 x & z \\
 \hline
 \text{rcd} & \\
 \hline
 x & z \\
 \hline
 \text{rab} & \\
 \hline
 \end{array} . \text{ Thus the boundaries are equal .}$$

Remark 3.1.5: The axioms (3.1.4)(i,ii,iii) are essentially the axioms for connection on a double category given in [S-1] . These axioms involve only the composition and not the additions or scalar multiplications of the algebroid structure . But the axioms (3.1.4)(iv,v) give relations between (Γ, Γ') and the additions and scalar multiplications . These axioms are equivalent to conditions on the folding operation given later in §3.2 and are not used until that section .

We go back to define a morphism between two special double algebroids with connections .

Definition 3.1.6: A morphism $\Psi : D \rightarrow E$ of special double algebroids with connections (Γ, Γ') , (Δ, Δ') is said to preserve the connections if and only if

$$\Delta \Psi_2 = \Psi_0 \Gamma , \Delta' \Psi_2 = \Psi_0 \Gamma' .$$

Such morphisms form the morphisms of the category of special double algebroids with connections, denoted by \underline{DA}' .

We gave in proposition (2.2.1) a functor from double algebroids to crossed modules (over algebroids), associating to D the crossed module (A, M, μ) with $A = D_2$ and M consisting of squares with boundary of the form $(1 \begin{smallmatrix} m \\ 0 \end{smallmatrix} 1)$. We have a

forgetful functor \underline{DA}' (special double algebroids with connection) \dashrightarrow (double algebroids). The composite functor $\underline{DA}' \dashrightarrow \underline{C}$ (crossed modules) will be written as γ .

Notice that in a special double algebroid, a thin structure implies a connection satisfying (3.1.4)(i,ii,iii)

where $\Gamma(a) = \theta(a \begin{smallmatrix} a \\ 1 \end{smallmatrix} 1)$, $\Gamma'(a) = \theta(1 \begin{smallmatrix} 1 \\ a \end{smallmatrix} a)$. To complete the

equivalence between these two structures, we prove first that in a special double algebroid a thin structure may be recovered from a connection satisfying only (3.1.4)(i,ii,iii). This result leads us to use connections instead of thin structures. The idea particularly in higher dimensions has been given in [B-H-1] in the double groupoid case, and partially in [S-1], [S-W-1], for double categories.

As mentioned above, the proof of the following theorem does not involve axioms (3.1.4)(iv,v) on connections.

Theorem 3.1.7: Let D be a special double algebroid with connection Γ, Γ' . Then there is a morphism of special double algebroids $\theta: \square D_1 \rightarrow D$, which is the identity on D_1

and such that $\Gamma a = \theta(a \begin{smallmatrix} a \\ 1 \end{smallmatrix} 1)$, $\Gamma' a = \theta(1 \begin{smallmatrix} 1 \\ b \end{smallmatrix} b)$.

Proof: For any $a, b, c, d \in D_1$ satisfying $cd = ab$, define functions $\theta_1, \theta_2 : \square D_1 \rightarrow D$ by

$$\theta_1 \left(\begin{array}{c} c \\ a \quad d \\ b \end{array} \right) = (\varepsilon_1 c * _2 \Gamma' d) * _1 (\Gamma a * _2 \varepsilon_1 b),$$

$$\theta_2 \left(\begin{array}{c} c \\ a \quad d \\ b \end{array} \right) = (\varepsilon_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 \varepsilon_2 d).$$

The two definitions make sense in terms of boundaries ; Appendix I give diagrams for these definitions and for the proof of the next lemma .

Lemma 3.1.8: The two definitions θ_1, θ_2 are equivalent , that is , $\theta_1 = \theta_2$.

Proof: Let $a, b, c, d \in D_1$ be such that $cd = ab$, then

$$\begin{aligned} \theta_1 \left(\begin{array}{c} c \\ a \quad d \\ b \end{array} \right) &= (\varepsilon_1 c * _2 \Gamma' d) * _1 (\Gamma a * _2 \varepsilon_1 b) \\ &= (\varepsilon_1 c * _2 \Gamma' d) * _1 \varepsilon_1 ab * _1 (\Gamma a * _2 \varepsilon_1 b) \quad \text{by the identity rule} \\ &= (\varepsilon_1 c * _2 \Gamma' d) * _1 (\Gamma' ab * _2 \Gamma cd) * _1 (\Gamma a * _2 \varepsilon_1 b) \\ &\hspace{15em} \text{by (3.1.4)(ii) and } cd = ab \\ &= (\varepsilon_1 c * _2 \Gamma' d) * _1 \{ [\Gamma' a * _2 (\varepsilon_2 a * _1 \Gamma' b)] * _2 [(\Gamma c * _1 \varepsilon_2 d) * _2 \Gamma d] \} * _1 (\Gamma a * _2 \varepsilon_1 b) \quad \text{by (3.1.4)(iii)} \\ &= (\varepsilon_1 c * _2 \Gamma' d) * _1 \{ [\Gamma' a * _2 (\varepsilon_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 \varepsilon_2 d)] * _2 \Gamma d \} * _1 (\Gamma a * _2 \varepsilon_1 b) \quad \text{by associativity} \\ &= \{ \{ \varepsilon_1 c * _1 [\Gamma' a * _2 (\varepsilon_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 \varepsilon_2 d)] \} * _2 (\Gamma' d * _1 \Gamma d) \} * _1 (\Gamma a * _2 \varepsilon_1 b) \quad \text{by (2.1.6)(ii)} \\ &= [\varepsilon_1 c * _1 [\Gamma' a * _2 (\varepsilon_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 \varepsilon_2 d)]] * _1 (\Gamma a * _2 \varepsilon_1 b) \quad \text{by (3.1.4)(ii)} \\ &= \varepsilon_1 c * _1 \{ [\Gamma' a * _2 [(\varepsilon_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 \varepsilon_2 d)]] * _1 (\Gamma a * _2 \varepsilon_1 b) \} \quad \text{by associativity} \\ &= \varepsilon_1 c * _1 \{ (\Gamma' a * _1 \Gamma a) * _2 [[(\varepsilon_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 \varepsilon_2 d)] * _1 \varepsilon_1 b] \} \} \quad \text{by (2.1.6)(ii)} \end{aligned}$$

$$\begin{aligned}
&= c_1 c * _1 [(c_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 c_2 d)] * _1 c_1 b \text{ by (3.1.4)(ii)} \\
&= (c_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 c_2 d) \text{ by the identity rule} \\
&= \theta_2 \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right). \text{ This is the complete proof of the lemma.}
\end{aligned}$$

Now we continue to prove theorem (3.1.7), that is, we prove θ satisfies the following:

$$i) \theta \left(a \begin{smallmatrix} l \\ l \end{smallmatrix} a \right) = \left(a \begin{smallmatrix} l \\ l \end{smallmatrix} a \right), \quad \theta \left(l \begin{smallmatrix} a \\ a \end{smallmatrix} l \right) = \left(l \begin{smallmatrix} a \\ a \end{smallmatrix} l \right);$$

$$ii) \theta \left(a \begin{smallmatrix} a \\ l \end{smallmatrix} l \right) = \left(a \begin{smallmatrix} a \\ l \end{smallmatrix} l \right), \quad \theta \left(l \begin{smallmatrix} l \\ a \end{smallmatrix} a \right) = \left(l \begin{smallmatrix} l \\ a \end{smallmatrix} a \right);$$

$$iii) \theta \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) +_1 \theta \left(a_1 \begin{smallmatrix} c \\ b \end{smallmatrix} d_1 \right) = \theta \left(a+a_1 \begin{smallmatrix} c \\ b \end{smallmatrix} d+d_1 \right);$$

$$iv) \theta \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) +_2 \theta \left(a \begin{smallmatrix} c_1 \\ b_1 \end{smallmatrix} d \right) = \theta \left(a \begin{smallmatrix} c+c_1 \\ b+b_1 \end{smallmatrix} d \right);$$

$$v) r \cdot _1 \theta \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) = \theta \left(ra \begin{smallmatrix} c \\ b \end{smallmatrix} rd \right);$$

$$vi) r \cdot _2 \theta \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) = \theta \left(a \begin{smallmatrix} rc \\ rb \end{smallmatrix} d \right);$$

$$vii) \theta \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) * _2 \theta \left(d \begin{smallmatrix} c' \\ b' \end{smallmatrix} e \right) = \theta \left(a \begin{smallmatrix} cc' \\ bb' \end{smallmatrix} d \right);$$

$$viii) \theta \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) * _1 \theta \left(a' \begin{smallmatrix} b \\ e \end{smallmatrix} d' \right) = \theta \left(aa' \begin{smallmatrix} c \\ e \end{smallmatrix} dd' \right).$$

The proof of (i), (ii) are easy. To prove (iii), we use the interchange law (2.1.6)(iii), distributive law, (2.1.7) and $\theta = \theta_2$;

$$\theta_2 \left(a \begin{smallmatrix} c \\ b \end{smallmatrix} d \right) +_1 \theta_2 \left(a_1 \begin{smallmatrix} c \\ b \end{smallmatrix} d_1 \right) = [(c_2 a * _1 \Gamma' b) * _2 (\Gamma c * _1 c_2 d)] +_1$$

$$[(c_2 a_1 * _1 \Gamma' b) * _2 (\Gamma c * _1 c_2 d_1)]$$

$$\begin{aligned}
&= [(\epsilon_2 a *_{1} \Gamma' b) +_{1} (\epsilon_2 a_1 *_{1} \Gamma' b)] *_{2} [(\Gamma c *_{1} \epsilon_2 d) +_{1} \\
&\quad (\Gamma c *_{1} \epsilon_2 d_1)] \quad \text{by (2.1.6)(iii)} \\
&= [(\epsilon_2 a +_{1} \epsilon_2 a_1) *_{1} \Gamma' b] *_{2} [\Gamma c *_{1} (\epsilon_2 d +_{1} \epsilon_2 d_1)] \\
&\quad \text{by distributivity} \\
&= (\epsilon_2 (a+a_1) *_{1} \Gamma' b) *_{2} (\Gamma c *_{1} \epsilon_2 (d+d_1)) \quad \text{by (2.1.7)} \\
&= \theta_2(a+a_1 \begin{smallmatrix} c \\ b \end{smallmatrix} d+d_1) .
\end{aligned}$$

To prove (iv) , we use (2.1.7), (2.1.6)(iv) , distributivity , and $\theta = \theta_1$;

$$\begin{aligned}
\theta_1(a \begin{smallmatrix} c \\ b \end{smallmatrix} d) +_2 \theta_1(a \begin{smallmatrix} c_1 \\ b_1 \end{smallmatrix} d) &= [(\epsilon_1 c *_{2} \Gamma' d) *_{1} (\Gamma a *_{2} \epsilon_1 b)] +_2 \\
&[(\epsilon_1 c_1 *_{2} \Gamma' d) *_{1} (\Gamma a *_{2} \epsilon_1 b_1)] \\
&= [(\epsilon_1 c *_{2} \Gamma' d) +_2 (\epsilon_1 c_1 *_{2} \Gamma' d)] *_{1} [(\Gamma a *_{2} \epsilon_1 b) +_2 \\
&\quad (\Gamma a *_{2} \epsilon_1 b_1)] \quad \text{by (2.1.6)(iv)} \\
&= [(\epsilon_1 c +_2 \epsilon_1 c_1) *_{2} \Gamma' d] *_{1} [\Gamma a *_{2} (\epsilon_1 b +_2 \epsilon_1 b_1)] \\
&\quad \text{by distributivity} \\
&= (\epsilon_1 (c + c_1) *_{2} \Gamma' d) *_{1} (\Gamma a *_{2} \epsilon_1 (b + b_1)) \quad \text{by (2.1.7)} \\
&= \theta_1(a \begin{smallmatrix} c+c_1 \\ b+b_1 \end{smallmatrix} d) .
\end{aligned}$$

To prove (v) , we use the rule (2.1.5)(ii) and $\theta = \theta_2$;

$$\begin{aligned}
\theta_2(ra \begin{smallmatrix} c \\ b \end{smallmatrix} rd) &= (\epsilon_2 ra *_{1} \Gamma' b) *_{2} (\Gamma c *_{1} \epsilon_2 rd) \\
&= (r \cdot_1 \epsilon_2 a *_{1} \Gamma' b) *_{2} (\Gamma c *_{1} r \cdot_1 \epsilon_2 d) \\
&= (r \cdot_1 (\epsilon_2 a *_{1} \Gamma' b)) *_{2} (r \cdot_1 (\Gamma c *_{1} \epsilon_2 d)) \\
&= r \cdot_1 [(\epsilon_2 a *_{1} \Gamma' b) *_{2} (\Gamma c *_{1} \epsilon_2 d)] \quad \text{by (2.1.5)(ii)} \\
&= r \cdot_1 \theta(a \begin{smallmatrix} c \\ b \end{smallmatrix} d) .
\end{aligned}$$

We can prove similarly that $\theta(a \begin{smallmatrix} rc \\ rb \end{smallmatrix} d) = r \cdot_2 \theta(a \begin{smallmatrix} c \\ b \end{smallmatrix} d)$

by using (2.1.5)(ii) and $\theta = \theta_1$.

For (vii), we use the interchange law (2.1.6)(ii), the identity rule, the associativity, (3.1.4)(ii), the equality $cdd' = abd' = aa'e$ and $\theta = \theta_1$;

$$\begin{aligned}
 \theta\left(a \begin{array}{c} cc' \\ bb' \end{array} e\right) &= (\epsilon_1 cc' * _2 \Gamma'e) * _1 (\Gamma a * _2 \epsilon_1 bb') \\
 &= (\epsilon_1 c * _2 \epsilon_1 c' * _2 \Gamma'e) * _1 \epsilon_1 cdb' * _1 (\Gamma a * _2 \epsilon_1 b * _2 \epsilon_1 b') \\
 &\quad \text{by the identity rule} \\
 &= (\epsilon_1 c * _2 (\epsilon_1 c' * _2 \Gamma'e)) * _1 (\epsilon_1 c * _2 \epsilon_1 d * _2 \epsilon_1 b') * _1 \\
 &\quad ((\Gamma a * _2 \epsilon_1 b) * _2 \epsilon_1 b') \quad \text{by the associativity} \\
 &= [\epsilon_1 c * _2 (\epsilon_1 c' * _2 \Gamma'e)] * _1 [(\epsilon_1 c * _2 \Gamma'd) * _2 (\Gamma d * _2 \epsilon_1 b')] * _1 \\
 &\quad [(\Gamma a * _2 \epsilon_1 b) * _2 \epsilon_1 b'] \quad \text{by (3.1.4)(ii)} \\
 &= [(\epsilon_1 c * _1 (\epsilon_1 c * _2 \Gamma'd)) * _2 ((\epsilon_1 c' * _2 \Gamma'e) * _1 (\Gamma d * _2 \epsilon_1 b'))] \\
 &\quad * _1 [(\Gamma a * _2 \epsilon_1 b) * _2 \epsilon_1 b'] \quad \text{by (2.1.6)(ii)} \\
 &= [(\epsilon_1 c * _2 \Gamma'd) * _1 (\Gamma a * _2 \epsilon_1 b)] * _2 [(\epsilon_1 c' * _2 \Gamma'e) * _1 \\
 &\quad (\Gamma d * _2 \epsilon_1 b') * _1 \epsilon_1 b'] \quad \text{by the identity rule and (2.1.6)(ii)} \\
 &= [(\epsilon_1 c * _2 \Gamma'd) * _1 (\Gamma a * _2 \epsilon_1 b)] * _2 [(\epsilon_1 c' * _2 \Gamma'e) * _1 \\
 &\quad (\Gamma d * _2 \epsilon_1 b')] \quad \text{by the identity rule} \\
 &= \theta_1\left(a \begin{array}{c} c \\ b \end{array} d\right) * _2 \theta_1\left(d \begin{array}{c} c' \\ b' \end{array} e\right) .
 \end{aligned}$$

We can prove similarly that $\theta\left(a \begin{array}{c} c \\ b \end{array} d\right) * _1 \theta\left(a' \begin{array}{c} b \\ e \end{array} d'\right) =$

$\theta\left(aa' \begin{array}{c} c \\ e \end{array} dd'\right)$, by using (3.1.4)(ii), the identity rule,

the interchange law (2.1.6)(ii), $cdd' = abd' = aa'e$ and $\theta = \theta_2$.

Then θ is a morphism. This is the complete proof of the theorem. \square

We move now in the next section to construct a functor $\lambda : \underline{C} \dashrightarrow \underline{DA}$ by using a "folding" operation, whose definition involves the connections.

2. THE FOLDING OPERATION:

In this section, we introduce on squares of a special double algebroid with connections D an operation which has the effect of "folding" all edges of $\alpha \in D$ onto the edge $\partial_1^0 \alpha$.

This operation Φ transforms α into an element of the associated crossed module γD .

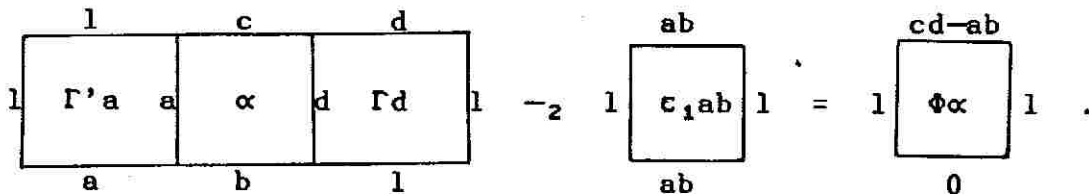
We define $\Phi: D \dashrightarrow D$ in the following way; given $\alpha \in D$ with boundary edges in the form



we define

$$\Phi\alpha = (\Gamma'a *_{2} \alpha *_{2} \Gamma d) -_{2} \epsilon_{1ab}.$$

It is easy to check that this composition and subtraction are defined. Simply, if α as above, then $\Phi\alpha$ has boundary in the form



Thus $\partial_1^0 \Phi\alpha = cd - ab$, $\partial_1^1 \Phi\alpha = 0$, $\partial_2^0 \Phi\alpha = 1$, $\partial_2^1 \Phi\alpha = 1$

and hence $\Phi\alpha \in \gamma D$.

Proposition 3.2.1: $\Phi\alpha = \alpha$ if and only if α is in γD . In particular $\Phi^2\alpha = \Phi\alpha$ for all $\alpha \in D$.

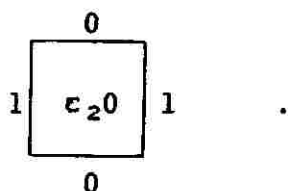
Proof: If $\Phi\alpha = \alpha$, then α has boundary edges given by

$(1 \begin{smallmatrix} m \\ 0 \end{smallmatrix} 1)$, for $m \in D_1 = D_2$ and then $\alpha \in \gamma D$ (by the

construction given in chapter II). The converse is clear. \square

We now develop relations between Φ and the operations of the special double algebroid D .

First, let $0^2 = c_2 0 \in D$, as in the diagram

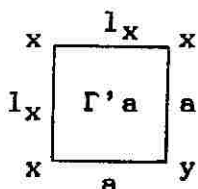


Proposition 3.2.2: Let $a \in D_1(x, y)$, then

i) $\Phi\Gamma'a = 0^2$, $\Phi\Gamma a = 0^2$,

ii) $\Phi c_1 a = 0^2$, $\Phi c_2 a = 0^2$.

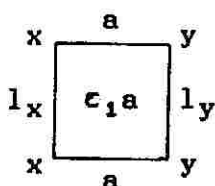
Proof: i) Since $a \in D_1(x, y)$, then $\Gamma'a$ has boundary in the form



$$\begin{aligned} \text{and then } \Phi\Gamma'a &= (\Gamma'l_x *_2 \Gamma'a *_2 \Gamma a) -_2 c_1 a \\ &= c_1 a -_2 c_1 a \quad \text{by (3.1.4)(ii)} \\ &= 0^2 . \end{aligned}$$

We can prove similarly that $\Phi\Gamma a = 0^2$.

ii) Since $a \in D_1(x, y)$, then $c_1 a$ has boundary edges given by



and then $\Phi \epsilon_1 a = (\Gamma' l_x * _2 \epsilon_1 a * _2 \Gamma l_y) -_2 \epsilon_1 a = 0^2$. Similarly we can prove that $\Phi \epsilon_2 a = 0^2$ by (3.1.4)(ii). \square

The following proposition is the main technical work required for the proof of the equivalence of categories given in the next sections.

Proposition 3.2.3: Let $\alpha, \beta \in D$ and $r \in R$, then the following hold whenever each left-hand side is defined:

i) $\Phi(\alpha +_1 \beta) = \Phi\alpha +_2 \Phi\beta$,

ii) $\Phi(\alpha +_2 \beta) = \Phi\alpha +_2 \Phi\beta$,

iii) $\Phi(\alpha * _1 \beta) = (\Phi\alpha * _2 \epsilon_1 \partial_2^1 \beta) +_2 (\epsilon_1 \partial_2^0 \alpha * _2 \Phi\beta)$,

iv) $\Phi(\alpha * _2 \beta) = (\epsilon_1 \partial_1^0 \alpha * _2 \Phi\beta) +_2 (\Phi\alpha * _2 \epsilon_1 \partial_1^1 \beta)$,

v) $\Phi(r \cdot_1 \alpha) = r \cdot_2 \Phi\alpha$, $\Phi(r \cdot_2 \alpha) = r \cdot_2 \Phi\alpha$.

(Appendix II gives diagrams for the proof of the above proposition).

Proof: i) If α, β have boundaries given by

$$\underline{\partial}\alpha = \begin{pmatrix} c \\ a & d \\ b \end{pmatrix}, \quad \underline{\partial}\beta = \begin{pmatrix} c \\ a_1 & d_1 \\ b \end{pmatrix},$$

$$\text{then } \Phi(\alpha +_1 \beta) = [\Gamma'(a+a_1) * _2 (\alpha +_1 \beta) * _2 \Gamma(d+d_1)] -_2 \epsilon_1(a+a_1)b$$

$$= [(\Gamma'a * _2 \alpha * _2 \Gamma d) +_2 (\Gamma'a_1 * _2 \beta * _2 \Gamma d_1)] -_2 [\epsilon_1 ab +_2 \epsilon_1 a_1 b]$$

by (3.1.4)(iv)

$$= [(\Gamma'a * _2 \alpha * _2 \Gamma d) -_2 \epsilon_1 ab] +_2 [(\Gamma'a_1 * _2 \beta * _2 \Gamma d_1) -_2 \epsilon_1 a_1 b]$$

$$= \Phi\alpha +_2 \Phi\beta.$$

ii) This follows from the algebroid rules for $+_2$, $*_2$.

iii) If α, β having boundaries given by

$$\underline{\partial}\alpha = \begin{pmatrix} c \\ a & d \\ b \end{pmatrix}, \quad \underline{\partial}\beta = \begin{pmatrix} b \\ a' & d' \\ e \end{pmatrix}, \quad \text{then } \alpha * _1 \beta \text{ has boundary}$$

edges in the form $\underline{\partial}(\alpha *_1 \beta) = \begin{pmatrix} aa' & c \\ & dd' \end{pmatrix} e$.

$$\begin{aligned}
\text{Then } \Phi(\alpha *_1 \beta) &= (\Gamma'aa' *_2 (\alpha *_1 \beta) *_2 \Gamma dd') -_2 c_1aa'e \\
&= \{[(\Gamma'a *_1 (c_1a *_2 \Gamma'a'))] *_2 (\alpha *_1 \beta) *_2 [(\Gamma d *_2 c_1d') *_1 \Gamma d]\} -_2 c_1aa'e && \text{by (3.1.4)(ii)} \\
&= \{[(\Gamma'a *_2 \alpha *_2 (\Gamma d *_2 c_1d'))] *_1 [(c_1a *_2 \Gamma'a') *_2 \beta *_2 \Gamma d']\} -_2 c_1aa'e && \text{by (2.1.6)(ii) and the associativity} \\
&= \{[(\Gamma'a *_2 \alpha *_2 \Gamma d) *_2 c_1d'] *_1 [c_1a *_2 (\Gamma'a' *_2 \beta *_2 \Gamma d')]\} -_2 (c_1aa'e *_1 c_1aa'e) && \text{by the associativity and the identity rule} \\
&= \{[(\Gamma'a *_2 \alpha *_2 \Gamma d) *_2 c_1d'] -_2 c_1aa'e\} *_1 \{[c_1a *_2 (\Gamma'a' *_2 \beta *_2 \Gamma d')] -_2 c_1aa'e\} && \text{by (2.1.6)(iv)} \\
&= \{[(\Gamma'a *_2 \alpha *_2 \Gamma d) *_2 c_1d'] -_2 c_1abd' +_2 c_1(abd' - aa'e)\} *_2 \{c_1a *_2 [(\Gamma'a' *_2 \beta *_2 \Gamma d') -_2 c_1a'e]\} && \text{by distributivity} \\
&= \{[(\Gamma'a *_2 \alpha *_2 \Gamma d) -_2 c_1ab] *_2 c_1d'\} +_2 c_1(abd' - aa'e)\} *_2 \{c_1a *_2 \Phi\beta\} && \text{by distributivity} \\
&= [(\Phi\alpha *_2 c_1d') +_2 c_1(abd' - aa'e)] *_2 [c_10 +_2 (c_1a *_2 \Phi\alpha)] && \text{by the identity rule} \\
&= [(\Phi\alpha *_2 c_1d') *_2 c_10] +_2 [c_1(abd' - aa'e) *_2 (c_1a *_2 \Phi\beta)] && \text{by (2.1.6)(iv)} \\
&= (\Phi\alpha *_2 c_1d') +_2 (c_1a *_2 \Phi\beta) && \text{by the identity rule} \\
&= (\Phi\alpha *_2 c_1 \partial_2^1 \beta) +_2 (c_1 \partial_2^0 \alpha *_2 \Phi\beta) .
\end{aligned}$$

iv) If α , β have boundaries given by

$$\underline{\partial}\alpha = \begin{pmatrix} a & c \\ & d \end{pmatrix} b, \quad \underline{\partial}\beta = \begin{pmatrix} d & c' \\ & e \end{pmatrix} b'$$

then $\alpha *_2 \beta$ has boundary edges in the form $\begin{pmatrix} a & cc' \\ & bb' \end{pmatrix} e$.

$$\begin{aligned}
\text{Now we compute } \Phi(\alpha *_2 \beta) &= [\Gamma'a *_2 (\alpha *_2 \beta) *_2 \Gamma e] -_2 c_1abb' \\
&= [(\Gamma'a *_2 \alpha) *_2 c_2d *_2 (\beta *_2 \Gamma e)] -_2 c_1abb'
\end{aligned}$$

by associativity and the identity rule

$$\begin{aligned}
&= [(\Gamma'a * _2 \alpha) * _2 (\Gamma'd * _1 \Gamma d) * _2 (\beta * _2 \Gamma e)] -_2 c_{1abb'} \\
&\qquad\qquad\qquad \text{by (3.1.4)(i)} \\
&= \{[c_{1c} * _1 (\Gamma'a * _2 \alpha)] * _2 (\Gamma'd * _1 \Gamma d) * _2 [(\beta * _2 \Gamma e) * _1 c_{1b'}]\} \\
&\quad -_2 c_{1abb'} \qquad\qquad\qquad \text{by the identity rule} \\
&= \{[(c_{1c} * _2 \Gamma'd) * _1 [(\Gamma'a * _2 \alpha) * _2 \Gamma d]] * _2 [(\beta * _2 \Gamma e) * _1 \\
&\quad c_{1b'}]\} -_2 c_{1abb'} \qquad\qquad\qquad \text{by (2.1.6)(ii)} \\
&= \{[c_{1c} * _2 \Gamma'd * _2 \beta * _2 \Gamma e] * _1 [(\Gamma'a * _2 \alpha * _2 \Gamma d * _2 c_{1b'})] -_2 \\
&\quad (c_{1abb'} * _1 c_{1abb'})\} \text{ by (2.1.6)(ii) and associativity} \\
&= \{[(c_{1c} * _2 \Gamma'd * _2 \beta * _2 \Gamma e) -_2 c_{1cdd'}] +_2 c_{1}(cdb' - abb')\} \\
&\quad * _1 \{[(\Gamma'a * _2 \alpha * _2 \Gamma d * _2 c_{1b'}) -_2 c_{1abb'}]\} \text{ by (2.1.6)(iv)} \\
&= \{[c_{1c} * _2 [(\Gamma'd * _2 \beta * _2 \Gamma e) -_2 c_{1db'}]] +_2 c_{1}(cdb' - abb')\} * _1 \\
&\quad \{[(\Gamma'a * _2 \alpha * _2 \Gamma d) -_2 c_{1ab}] * _2 c_{1b'}\} \text{ by the identity rule} \\
&= [(c_{1c} * _2 \Phi\beta) +_2 c_{1}(cdb' - abb')] * _1 [\Phi\alpha * _2 c_{1b'}] \\
&= [(c_{1c} * _2 \Phi\beta) +_2 c_{1}(cdb' - abb')] * _1 [c_{10} +_2 (\Phi\alpha * _2 c_{1b'})] \\
&= [(c_{1c} * _2 \Phi\beta) * _1 c_{10}] +_2 [c_{1}(cdb' - abb') * _1 (\Phi\alpha * _2 c_{1b'})] \\
&\qquad\qquad\qquad \text{by (2.1.6)(iv)} \\
&= (c_{1c} * _2 \Phi\beta) +_2 (\Phi\alpha * _2 c_{1b'}) \text{ by the identity rule} \\
&= (c_{1\partial_1^0\alpha} * _2 \Phi\beta) +_2 (\Phi\alpha * _2 c_{1\partial_1^1\beta}) .
\end{aligned}$$

It is clear that (v) is satisfied by using (3.1.4)(v) for the first rule , and the algebroid laws for the second . This completes the proof of the proposition . \square

We are ready now to construct a functor say λ from the category \underline{C} of crossed modules (over algebroids) to the category $\underline{DA}^!$ of special double algebroids with connections .

3. THE FUNCTOR $\lambda: C \rightarrow DA'$:

In this section , we construct a special double algebroid with connections from a crossed module (over an algebroid) by using the folding operation .

Let (A, M, μ) be a crossed module (over an algebroid) , and let $D_0 = A_0$ (the set of objects) , $D_1 = D_2 = A$ (the algebroid of arrows of A) . Since $\square D_1 = \square A$ is a special double algebroid with thin structure , then the folding operation Φ applies to it and so for $\underline{a} \in \square A$ with boundary edges $(a_1 \begin{smallmatrix} a_3 \\ a_2 \end{smallmatrix} a_4)$, we have

$\partial_1^0 \Phi \underline{a} = a_3 a_4 - a_1 a_2$. We let D be given by

$D = \{(\underline{a}, \zeta) : \underline{a} \in \square D_1 , \zeta \in M \text{ such that } \mu \zeta = \partial_1^0 \Phi \underline{a}\}$. Thus we

can define the maps $\epsilon_j , \partial_1^i , \partial_2^i , \Gamma , \Gamma'$ (for $j = 1, 2$ and $i = 0, 1$) in the following way :

if $a_1 \in D_1$, define $\epsilon_j a_1 = (\epsilon_j a_1, 0)$, where ϵ_j is defined by (2.1.7) . Clearly $\epsilon_j a_1 \in D$ (since $\Phi \epsilon_j a_1 = 0^2$) . Also define

$\partial_1^i , \partial_2^i : D \rightarrow D_1 = D_2$ by : if $(\underline{a}, \zeta) \in D$, then the boundary

edges of (\underline{a}, ζ) are to be those of \underline{a} , i.e. $\partial(\underline{a}, \zeta) = \partial \underline{a}$.

Define a thin structure $\theta: \square D_1 \rightarrow D$ by $\theta(\underline{a}) = (\underline{a}, 0)$ (here

$0 \in M(\partial_1^0 \partial_2^0 \underline{a} , \partial_1^1 \partial_2^1 \underline{a})$).

We define now some algebraic structure on elements of D .

First we define two additions ; namely $+_1 , +_2$.

For $+_1$, let $(\underline{a}, \zeta) , (\underline{b}, \eta) \in D$ with $\partial_1^i \underline{a} = \partial_1^i \underline{b}$; then we

define $(\underline{a}, \zeta) +_1 (\underline{b}, \eta) = (\underline{a} +_1 \underline{b}, \zeta + \eta)$.

For $+_2$, let $(\underline{a}, \zeta) , (\underline{b}, \eta) \in D$ with $\partial_2^j \underline{a} = \partial_2^j \underline{b}$; we define

$$(\underline{a}, \zeta) +_2 (\underline{b}, \eta) = (\underline{a} +_2 \underline{b}, \zeta + \eta) .$$

a We define two scalar multiplications: let $(\underline{a}, \zeta) \in D$ and $r \in R$; then $r \cdot_1 (\underline{a}, \zeta) = (r \cdot_1 \underline{a}, r \cdot \zeta)$, $r \cdot_2 (\underline{a}, \zeta) = (r \cdot_2 \underline{a}, r \cdot \zeta)$.

Note that these definitions make sense . Thus we have

$$\partial_1^0 \Phi(\underline{a} +_1 \underline{b}) = \partial_1^0 \Phi \underline{a} +_2 \partial_1^0 \Phi \underline{b} = \mu \zeta + \mu \eta = \mu(\zeta + \eta) ,$$

$$\partial_1^0 \Phi(r \cdot_1 \underline{a}) = \partial_1^0 (r \cdot_2 \Phi \underline{a}) = r \cdot \partial_1^0 \Phi \underline{a} = r \cdot \mu \zeta = \mu(r \cdot \zeta) .$$

Next , we define two compositions :

let (\underline{a}, ζ) , $(\underline{b}, \eta) \in D$ with $\partial_1^1 \underline{a} = \partial_1^0 \underline{b}$; then we define

$$(\underline{a}, \zeta) *_1 (\underline{b}, \eta) = (\underline{a} *_1 \underline{b}, \zeta \partial_2^1 \underline{b} + \partial_2^0 \underline{a} \eta) . \text{ If } (\underline{a}, \zeta), (\underline{b}, \eta) \in D$$

with $\partial_2^1 \underline{a} = \partial_2^0 \underline{b}$, then we define

$$(\underline{a}, \zeta) *_2 (\underline{b}, \eta) = (\underline{a} *_2 \underline{b}, \partial_1^0 \underline{a} \eta + \zeta \partial_1^1 \underline{b}) .$$

We must verify the appropriate boundary condition , we have

$$\partial_1^0 \Phi(\underline{a} *_1 \underline{b}) = \partial_1^0 [(\Phi \underline{a} *_2 \zeta \partial_2^1 \underline{b}) + (\zeta \partial_2^0 \underline{a} *_2 \Phi \underline{b})]$$

$$= (\partial_1^0 \Phi \underline{a} *_2 \partial_1^0 \zeta \partial_2^1 \underline{b}) +_2 (\partial_1^0 \zeta \partial_2^0 \underline{a} *_2 \partial_1^0 \Phi \underline{b})$$

$$= (\mu \zeta *_2 \partial_2^1 \underline{b}) +_2 (\partial_2^0 \underline{a} *_2 \mu \eta) = \mu(\zeta \partial_2^1 \underline{b} + \partial_2^0 \underline{a} \eta)$$

by (1.3.1)(iii) and (1.3.2)(i) .

Thus we are ready to give the main result of this section .

Proposition 3.3.1: The above structure 'is a special double algebroid with connections .

Proof: First , we want to verify that $(+_1, *_1, \cdot_1)$ and $(+_2, *_2, \cdot_2)$ each give an algebroid structure , that is , $*_1$, $*_2$ are R-bilinear morphisms and satisfy the associative condition . It is clear that $*_1$ is an R-bilinear morphism .

Thus $(+_1, *_1, \cdot_1)$ an R-algebroid if $*_1$ satisfies associativity .

Let $(\underline{a}, \zeta), (\underline{b}, \eta), (\underline{c}, \xi) \in D$. Then

$$\begin{aligned} [(\underline{a}, \zeta) *_1 (\underline{b}, \eta)] *_1 (\underline{c}, \xi) &= [\underline{a} *_1 \underline{b} , \zeta \partial_2^1 \underline{b} + \partial_2^0 \underline{a} \eta] *_1 (\underline{c}, \xi) \\ &= [(\underline{a} *_1 \underline{b}) *_1 \underline{c} , (\zeta \partial_2^1 \underline{b} + \partial_2^0 \underline{a} \eta) \partial_2^1 \underline{c} + \partial_2^0 (\underline{a} *_1 \underline{b}) \xi] . \end{aligned}$$

On the other hand ;

$$\begin{aligned} (\underline{a}, \zeta) *_1 [(\underline{b}, \eta) *_1 (\underline{c}, \xi)] &= (\underline{a}, \zeta) *_1 [(\underline{b} *_1 \underline{c}) , \eta \partial_2^1 \underline{c} + \partial_2^0 \underline{b} \xi] \\ &= [\underline{a} *_1 (\underline{b} *_1 \underline{c}) , \zeta \partial_2^1 (\underline{b} *_1 \underline{c}) + \partial_2^0 \underline{a} (\eta \partial_2^1 \underline{c} + \partial_2^0 \underline{b} \xi)] . \end{aligned}$$

Clearly $(\underline{a} *_1 \underline{b}) *_1 \underline{c} = \underline{a} *_1 (\underline{b} *_1 \underline{c})$. To prove that

$$\begin{aligned} (\zeta \partial_2^1 \underline{b} + \partial_2^0 \underline{a} \eta) \partial_2^1 \underline{c} + \partial_2^0 (\underline{a} *_1 \underline{b}) \xi &= \zeta \partial_2^1 (\underline{b} *_1 \underline{c}) + \\ \partial_2^0 \underline{a} (\eta \partial_2^1 \underline{c} + \partial_2^0 \underline{b} \xi) &, \text{ we start with the right hand side ;} \end{aligned}$$

$$= \zeta \partial_2^1 (\underline{b} *_1 \underline{c}) + (\partial_2^0 \underline{a} \eta) \partial_2^1 \underline{c} + \partial_2^0 \underline{a} (\partial_2^0 \underline{b} \xi) \text{ by (1.3.1)(i,iii)}$$

$$= (\zeta \partial_2^1 \underline{b}) \partial_2^1 \underline{c} + (\partial_2^0 \underline{a} \eta) \partial_2^1 \underline{c} + \partial_2^0 \underline{a} (\partial_2^0 \underline{b} \xi) \text{ by (1.3.1)(i,iii)}$$

$$= (\zeta \partial_2^1 \underline{b} + \partial_2^0 \underline{a} \eta) \partial_2^1 \underline{c} + \partial_2^0 (\underline{a} *_1 \underline{b}) \xi \text{ by (1.3.1)(i,iii)}$$

= left hand side . Then

$$[(\underline{a}, \zeta) *_1 (\underline{b}, \eta)] *_1 (\underline{c}, \xi) = (\underline{a}, \zeta) *_1 [(\underline{b}, \eta) *_1 (\underline{c}, \xi)] .$$

The verification of the associativity with respect to $*_2$ is

similar to that of $*_1$. Thus $(+_2 , *_2 , \cdot_2)$ is an

R-algebroid . So we get algebroid structures for each of these two kind of operations .

Next , we want to verify the relations between these operations , and the rules for connections .

For the rules (2.1.3) , (2.1.4) the proofs are obvious ,
since $D_1 = D_2$. Now we verify the rule (2.1.5)(i-iii).

Let $(\underline{a}, \zeta), (\underline{b}, \eta) \in D$, then $(\underline{a}, \zeta) +_2 (\underline{b}, \eta) = (\underline{a} +_2 \underline{b}, \zeta + \eta)$ and
hence $r \cdot_1 (\underline{a} +_2 \underline{b}, \zeta + \eta) = (r \cdot_1 (\underline{a} +_2 \underline{b}) , r \cdot_1 (\zeta + \eta))$
 $= [(r \cdot_1 \underline{a} +_2 r \cdot_1 \underline{b}) , ((r \cdot \zeta) + (r \cdot \eta))]$
 $= ((r \cdot_1 \underline{a}) , (r \cdot \zeta)) +_2 ((r \cdot_1 \underline{b}) , (r \cdot \eta))$
 $= r \cdot_1 (\underline{a} , \zeta) +_2 r \cdot_1 (\underline{b} , \eta) .$

We prove similarly that

$r \cdot_2 [(\underline{a} , \zeta) +_1 (\underline{b} , \eta)] = r \cdot_2 (\underline{a} , \zeta) +_1 r \cdot_2 (\underline{b} , \eta) ,$
if $(\underline{a} , \zeta) +_1 (\underline{b} , \eta)$ is defined . Thus the rule (2.1.5)(i) is
satisfied .

For (2.1.5)(ii) , suppose given $(\underline{a}, \zeta) , (\underline{b}, \eta)$ such that
 $(\underline{a}, \zeta) *_2 (\underline{b}, \eta)$ is defined . Then

$$\begin{aligned} r \cdot_1 [(\underline{a}, \zeta) *_2 (\underline{b}, \eta)] &= r \cdot_1 [(\underline{a} *_2 \underline{b}) , \begin{matrix} \partial_1^0 \underline{a} \\ \eta \end{matrix} + \begin{matrix} \partial_1^1 \underline{b} \\ \zeta \end{matrix}] \\ &= (r \cdot_1 (\underline{a} *_2 \underline{b}) , r \cdot (\begin{matrix} \partial_1^0 \underline{a} \\ \eta \end{matrix} + \begin{matrix} \partial_1^1 \underline{b} \\ \zeta \end{matrix})) \\ &= ((r \cdot_1 \underline{a} *_2 r \cdot_1 \underline{b}), (r \cdot \begin{matrix} \partial_1^0 \underline{a} \\ \eta \end{matrix} + (r \cdot \begin{matrix} \partial_1^1 \underline{b} \\ \zeta \end{matrix}))) \text{ by (1.3.1)(iv)} \\ &= [((r \cdot_1 \underline{a}) *_2 (r \cdot_1 \underline{b})), (\begin{matrix} \partial_1^0 (r \cdot_1 \underline{a}) \\ (r \cdot \eta) \end{matrix} +_2 (r \cdot \zeta) \begin{matrix} \partial_1^1 (r \cdot_1 \underline{b}) \end{matrix})] \\ &\qquad\qquad\qquad \text{by bilinearity} \\ &= (r \cdot_1 \underline{a} , r \cdot \zeta) *_2 (r \cdot_1 \underline{b} , r \cdot \eta) \\ &= (r \cdot_1 (\underline{a}, \zeta)) *_2 (r \cdot_1 (\underline{b}, \eta)) . \text{ Similarly for the second part} \\ &\text{of (2.1.5)(ii).} \end{aligned}$$

Finally , for (2.1.5)(iii) , given $(\underline{a}, \zeta) \in D$, then

$$\begin{aligned} r \cdot_2 [s \cdot_1 (\underline{a}, \zeta)] &= r \cdot_2 [s \cdot_1 \underline{a} , s \cdot \zeta] \\ &= [r \cdot_2 (s \cdot_1 \underline{a}), r \cdot (s \cdot \zeta)] = [s \cdot_1 (r \cdot_2 \underline{a}) , s \cdot (r \cdot \zeta)] \\ &= s \cdot_1 [r \cdot_2 \underline{a} , r \cdot \zeta] = s \cdot_1 (r \cdot_2 (\underline{a}, \zeta)) . \end{aligned}$$

Next , we want to verify the interchange laws (2.1.6)(i-iv) .

For (2.1.6)(i) , let $(\underline{a}, \zeta), (\underline{b}, \eta), (\underline{c}, \xi), (\underline{d}, \psi) \in D$ such that

$(\underline{a}, \zeta) +_1 (\underline{b}, \eta)$, $(\underline{a}, \zeta) +_2 (\underline{c}, \xi)$, $(\underline{b}, \eta) +_2 (\underline{d}, \psi)$,

$(\underline{c}, \xi) +_1 (\underline{d}, \psi)$ are defined , then

$$[(\underline{a}, \zeta) +_1 (\underline{b}, \eta)] +_2 [(\underline{c}, \xi) +_1 (\underline{d}, \psi)] = (\underline{a} +_1 \underline{b} , \zeta + \eta) +_2 (\underline{c} +_1 \underline{d} , \xi + \psi)$$

$$= [(\underline{a} +_1 \underline{b}) +_2 (\underline{c} +_1 \underline{d}) , (\zeta + \eta) + (\xi + \psi)]$$

$$= [(\underline{a} +_2 \underline{c}) +_1 (\underline{b} +_2 \underline{d}) , (\zeta + \xi) + (\eta + \psi)]$$

$$= (\underline{a} +_2 \underline{c} , \zeta + \xi) +_1 (\underline{b} +_2 \underline{d} , \eta + \psi)$$

$$= ((\underline{a}, \zeta) +_2 (\underline{c}, \xi)) +_1 ((\underline{b}, \eta) +_2 (\underline{d}, \psi)) .$$

For (2.1.6)(ii) , let $(\underline{a}, \zeta), (\underline{b}, \eta), (\underline{c}, \xi), (\underline{d}, \psi) \in D$ such that

$(\underline{a}, \zeta) *_1 (\underline{b}, \eta)$, $(\underline{a}, \zeta) *_2 (\underline{c}, \xi)$, $(\underline{b}, \eta) *_2 (\underline{d}, \psi)$, $(\underline{c}, \xi) *_1 (\underline{d}, \psi)$

are defined , then

$$((\underline{a}, \zeta) *_1 (\underline{b}, \eta)) *_2 ((\underline{c}, \xi) *_1 (\underline{d}, \psi)) =$$

$$(\underline{a} *_1 \underline{b} , \zeta \frac{\partial^1 \underline{b}}{\partial^2 \underline{a}} + \frac{\partial^0 \underline{a}}{\partial^2 \underline{a}} \eta) *_2 (\underline{c} *_1 \underline{d} , \xi \frac{\partial^1 \underline{d}}{\partial^2 \underline{c}} + \frac{\partial^0 \underline{c}}{\partial^2 \underline{c}} \psi) =$$

$$[(\underline{a} *_1 \underline{b}) *_2 (\underline{c} *_1 \underline{d}) , \frac{\partial^0 (\underline{a} *_1 \underline{b})}{\partial^1} (\xi \frac{\partial^1 \underline{d}}{\partial^2 \underline{c}} + \frac{\partial^0 \underline{c}}{\partial^2 \underline{c}} \psi) +$$

$$(\zeta \frac{\partial^1 \underline{b}}{\partial^2 \underline{a}} + \frac{\partial^0 \underline{a}}{\partial^2 \underline{a}} \eta) \frac{\partial^1 (\underline{c} *_1 \underline{d})}{\partial^1}]$$

$$= [(\underline{a} *_2 \underline{c}) *_1 (\underline{b} *_2 \underline{d}) , \frac{\partial^0 \underline{a}}{\partial^1} (\xi \frac{\partial^1 \underline{d}}{\partial^2 \underline{c}} + \frac{\partial^0 \underline{c}}{\partial^2 \underline{c}} \psi) +$$

$$(\zeta \frac{\partial^1 \underline{b}}{\partial^2 \underline{a}} + \frac{\partial^0 \underline{a}}{\partial^2 \underline{a}} \eta) \frac{\partial^1 \underline{d}}{\partial^1}]$$

$$= [(\underline{a} *_2 \underline{c}) *_1 (\underline{b} *_2 \underline{d}) , (\frac{\partial^0 \underline{a}}{\partial^1} \xi) \frac{\partial^1 \underline{d}}{\partial^2 \underline{c}} + \frac{\partial^0 \underline{a}}{\partial^1} \frac{\partial^0 \underline{c}}{\partial^2 \underline{c}} \psi +$$

$$\zeta \frac{\partial^1 \underline{b}}{\partial^2 \underline{a}} \frac{\partial^1 \underline{d}}{\partial^1} + \frac{\partial^0 \underline{a}}{\partial^2 \underline{a}} (\eta \frac{\partial^1 \underline{d}}{\partial^1})] \quad \text{by (1.3.1)(i,iii) .}$$

On the other hand ;

$$[(\underline{a}, \zeta) *_2 (\underline{c}, \xi)] *_1 [(\underline{b}, \eta) *_2 (\underline{d}, \psi)] =$$

$$\begin{aligned}
& [\underline{a} * _2 \underline{c} , \partial_{1\underline{a}}^0 \underline{\epsilon} + \zeta \partial_{1\underline{c}}^1] * _1 [\underline{b} * _2 \underline{d} , \partial_{1\underline{b}}^0 \underline{\psi} + \eta \partial_{1\underline{d}}^1] = \\
& [(\underline{a} * _2 \underline{c}) * _1 (\underline{b} * _2 \underline{d}) , (\partial_{1\underline{a}}^0 \underline{\epsilon} + \zeta \partial_{1\underline{c}}^1) \partial_{2\underline{b} * _2 \underline{d}}^1] + \\
& \partial_{2\underline{a} * _2 \underline{c}}^0 (\partial_{1\underline{b}}^0 \underline{\psi} + \eta \partial_{1\underline{d}}^1)] = \\
& [(\underline{a} * _2 \underline{c}) * _1 (\underline{b} * _2 \underline{d}) , (\partial_{1\underline{a}}^0 \underline{\epsilon}) \partial_{2\underline{d}}^1 + (\zeta \partial_{1\underline{c}}^1) \partial_{2\underline{d}}^1 + \\
& \partial_{2\underline{a}}^0 (\partial_{1\underline{b}}^0 \underline{\psi}) + \partial_{2\underline{a}}^0 (\eta \partial_{1\underline{d}}^1)] \text{ by (1.3.1)(i,iii) .}
\end{aligned}$$

In order for these to be equal , we need ;

$$\begin{aligned}
& \zeta \partial_{1\underline{c}}^1 \partial_{2\underline{d}}^1 + \partial_{2\underline{a}}^0 \partial_{1\underline{b}}^0 \underline{\psi} = \partial_{1\underline{a}}^0 \partial_{2\underline{c}}^0 \underline{\psi} + \zeta \partial_{2\underline{b}}^1 \partial_{1\underline{d}}^1 \\
\text{i.e. } & \zeta \partial_{1\underline{c}}^1 \partial_{2\underline{d}}^1 - \zeta \partial_{2\underline{b}}^1 \partial_{1\underline{d}}^1 = \partial_{1\underline{a}}^0 \partial_{2\underline{c}}^0 \underline{\psi} - \partial_{2\underline{a}}^0 \partial_{1\underline{b}}^0 \underline{\psi} \\
\text{i.e. } & \zeta \partial_{1\underline{c}}^1 \partial_{2\underline{d}}^1 - \partial_{2\underline{b}}^1 \partial_{1\underline{d}}^1 = \partial_{1\underline{a}}^0 \partial_{2\underline{c}}^0 - \partial_{2\underline{a}}^0 \partial_{1\underline{b}}^0 \underline{\psi} \\
\text{i.e. } & \zeta \partial_{1\underline{d}}^0 \partial_{2\underline{d}}^1 - \partial_{2\underline{d}}^0 \partial_{1\underline{d}}^1 = \partial_{1\underline{a}}^0 \partial_{2\underline{a}}^1 - \partial_{2\underline{a}}^0 \partial_{1\underline{a}}^1 \underline{\psi} \\
\text{i.e. } & \zeta \underline{\phi}_d = \underline{\phi}_a \underline{\psi} .
\end{aligned}$$

The last equation follows from the crossed module rule (1.3.2)(ii) , since both sides are $\zeta * \psi$.

For (2.1.6)(iii) , let $(\underline{a}, \zeta), (\underline{b}, \eta), (\underline{c}, \epsilon), (\underline{d}, \psi) \in D$ such that $(\underline{a}, \zeta) * _2 (\underline{b}, \eta)$, $(\underline{c}, \epsilon) * _2 (\underline{d}, \psi)$, $(\underline{a}, \zeta) + _1 (\underline{c}, \epsilon)$, $(\underline{b}, \eta) + _1 (\underline{d}, \psi)$ are defined , then

$$\begin{aligned}
& [(\underline{a}, \zeta) * _2 (\underline{b}, \eta)] + _1 [(\underline{c}, \epsilon) * _2 (\underline{d}, \psi)] \\
& = [\underline{a} * _2 \underline{b} , \partial_{1\underline{a}}^0 \underline{\eta} + \zeta \partial_{1\underline{b}}^1] + _1 [\underline{c} * _2 \underline{d} , \partial_{1\underline{c}}^0 \underline{\psi} + \epsilon \partial_{1\underline{d}}^1] \\
& = [(\underline{a} * _2 \underline{b}) + (\underline{c} * _2 \underline{d}) , (\partial_{1\underline{a}}^0 \underline{\eta} + \zeta \partial_{1\underline{b}}^1) + (\partial_{1\underline{c}}^0 \underline{\psi} + \epsilon \partial_{1\underline{d}}^1)]
\end{aligned}$$

$$= [(\underline{a} +_1 \underline{c}) *_2 (\underline{b} +_1 \underline{d}), (\partial_{1^1}^0 \underline{a} \eta + \partial_{1^1}^0 \underline{c} \psi) + (\zeta \partial_{1^1}^1 \underline{b} + \xi \partial_{1^1}^1 \underline{d})]$$

$$= [(\underline{a} +_1 \underline{c}) *_2 (\underline{b} +_1 \underline{d}), \partial_{1^1}^0 (\underline{a} +_1 \underline{c}) (\eta + \psi) + (\zeta + \xi) \partial_{1^1}^1 \underline{d}]$$

by (1.3.1)(ii) and the above hypothesis

$$= [(\underline{a} +_1 \underline{c}) *_2 (\underline{b} +_1 \underline{d}), \partial_{1^1}^0 (\underline{a} +_1 \underline{c}) (\eta + \psi) + (\zeta + \xi) \partial_{1^1}^1 (\underline{b} +_1 \underline{d})]$$

$$= [\underline{a} +_1 \underline{c}, \zeta + \xi] *_2 [\underline{b} +_1 \underline{d}, \eta + \psi].$$

We can use a similar argument to verify (2.1.6)(iv).

It is clear that τ_j satisfy the rule (2.1.7), and θ satisfy the conditions (3.1.4)(i-v). This completes the proof. \square

Thus any crossed module (over an algebroid) gives a special double algebroid with connections. If (A, M, μ) , (A', M', μ') are two crossed modules (over algebroids) and $(\alpha, \beta) : (A, M, \mu) \dashrightarrow (A', M', \mu')$ is a morphism, then there exist a morphism $(\lambda\alpha, \epsilon\beta, I) : (D, D_1, D_2, D_0) \dashrightarrow (D', D_1', D_2', D_0')$ (since $A = D_1 = D_2$, $A' = D_1' = D_2'$, $A_0 = D_0$, $A_0' = D_0'$ and D, D' have been constructed from (A, M) , (A', M') respectively).

Thus there exist a functor λ from the category of crossed modules (over algebroids) \underline{C} to the category of special double algebroids with connections \underline{DA}' , that is we have a functor

$$\lambda : \underline{C} \dashrightarrow \underline{DA}'.$$

4. THE EQUIVALENCE OF CATEGORIES:

In this section, we want to prove the main result, which is the equivalence of the two categories \underline{C} , \underline{DA}' .

Theorem 3.4.1: The functors γ , λ defined previously form an adjoint equivalence

$$\gamma : \underline{DA} \overset{\lambda}{\longleftarrow} \underline{C} : \lambda .$$

Proof: First , we want to prove that $\gamma\lambda$ is naturally equivalent to the identity , that is , $\gamma\lambda \cong 1$.

Let (A, M, μ) be an object of \underline{C} and let $(A', M', \mu') = \gamma\lambda(A, M, \mu)$. Then $A_0 = A'_0$ and $A = A'$. It is clear that M' is defined on the same set of objects A_0 . Define a map $g: M \rightarrow M'$ by

$$g(m) = (m; l \begin{matrix} \mu m \\ 0 \end{matrix} l) , \text{ and let } I: A \rightarrow A' \text{ be the identity map .}$$

We want now to prove that $(I, g): (A, M, \mu) \rightarrow (A', M', \mu')$ is a crossed module morphism , that is $I\mu = \mu'g$ and g preserves the actions . Clearly I, g are algebroid morphisms and $\mu'g = I\mu$. So it is enough to show that (I, g) preserves the actions .

Take $m: x \rightarrow y \in M(x, y)$ and let $b: y \rightarrow z \in A(y, z)$. Thus

$$\begin{aligned} g(m^b) &= (m^b; l \begin{matrix} (\mu m)^b \\ 0 \end{matrix} l) \quad \text{by (1.3.2)(i)} \\ &= (m; l \begin{matrix} \mu m \\ 0 \end{matrix} l) *_2 \epsilon_1 b = (m; l \begin{matrix} \mu m \\ 0 \end{matrix} l)^b = g(m)^b . \end{aligned}$$

We prove similarly that $g(b^m) = b^g(m)$.

We define now a map $(I, f): (A', M', \mu') \rightarrow (A, M, \mu)$ such that (I, g) , (I, f) are inverse to each other . Let $I: A' \rightarrow A$ be the identity map and define $f: M' \rightarrow M$ by

$$f(m; l \begin{matrix} \mu m \\ 0 \end{matrix} l) = m .$$

Clearly I, f are algebroid morphisms and $\mu f = \mu'$. Thus (I, f) is a crossed module morphism if it preserves the action , that is ,

$$\text{let } (m; l \begin{matrix} \mu m \\ 0 \end{matrix} l) \in M' \text{ and } b \in A' . \text{ Then}$$

$$\begin{aligned}
f[(m; l \begin{smallmatrix} \mu m \\ 0 \end{smallmatrix} 1)^b] &= f[(m; l \begin{smallmatrix} \mu m \\ 0 \end{smallmatrix} 1) *_2 e_1 b] = f[(m^b; l \begin{smallmatrix} (\mu m)^b \\ 0 \end{smallmatrix} 1)] \\
&= f(m^b; l \begin{smallmatrix} \mu(m^b) \\ 0 \end{smallmatrix} 1) = m^b = [f(m; l \begin{smallmatrix} \mu m \\ 0 \end{smallmatrix} 1)]^b .
\end{aligned}$$

It is clear that $(I, g), (I, f)$ are inverse to each other .
Therefore $\gamma\lambda$ is naturally equivalent to the identity .

Second , we want to show that $\lambda\gamma$ is naturally equivalent to the identity , that is , $1 \cong \lambda\gamma$.

Let D be an object of $\underline{DA}^!$ and let $E = \lambda\gamma(D)$. Then $D_0 = E_0$,
 $D_1 = D_2 = E_1 = E_2$. We define $\eta: D \dashrightarrow E$ to be the identity on
 D_0 and $D_1 = D_2$ and on D as follows :

let $\alpha \in D$, define $\eta(\alpha) = (\underline{\partial}\alpha , \Phi\alpha)$. First we prove ;

Lemma 3.4.1: The map η is a morphism of double R -algebroid with connections (Γ, Γ') .

Proof: It suffices to prove that η preserves $+_1$, $+_2$, $*_1$,
 $*_2$, \cdot_1 , \cdot_2 , and the connection Γ , Γ' .

For $+_1$, let $\alpha, \beta \in D$ such that $\alpha +_1 \beta$ is defined , then

$$\eta(\alpha +_1 \beta) = [\underline{\partial}(\alpha +_1 \beta) , \Phi(\alpha +_1 \beta)] = (\underline{\partial}\alpha +_1 \underline{\partial}\beta , \Phi\alpha + \Phi\beta)$$

(since $\Phi\alpha, \Phi\beta \in \gamma(D)$)

$$= (\underline{\partial}\alpha , \Phi\alpha) +_1 (\underline{\partial}\beta , \Phi\beta) = \eta\alpha +_1 \eta\beta .$$

We can prove similarly that $\eta(\alpha +_2 \beta) = \eta\alpha +_2 \eta\beta$, if $\alpha +_2 \beta$ is defined .

For $*_1$, let $\alpha, \beta \in D$ such that α, β have boundaries in the

form $(\begin{smallmatrix} c \\ a \quad d \\ b \end{smallmatrix})$, $(\begin{smallmatrix} b \\ a' \quad d' \\ e \end{smallmatrix})$ respectively , then

$$\begin{aligned}
\eta(\alpha *_1 \beta) &= [\underline{\partial}(\alpha *_1 \beta) , \Phi(\alpha *_1 \beta)] \\
&= (\underline{\partial}\alpha *_1 \underline{\partial}\beta , (\Phi\alpha)^{d'} + a(\Phi\beta)) \quad \text{by (3.2.3)(iii)} .
\end{aligned}$$

On the other hand ;

$$\eta\alpha *_1 \eta\beta = (\underline{\partial}\alpha , \Phi\alpha) *_1 (\underline{\partial}\beta , \Phi\beta)$$

$$= (\underline{\partial}\alpha *_{1} \underline{\partial}\beta, (\Phi\alpha)^d + a(\Phi\beta)) = \eta(\alpha *_{1} \beta) .$$

We prove similarly that $\eta(\alpha *_{2} \beta) = \eta\alpha *_{2} \eta\beta$, if $\alpha *_{2} \beta$ is defined .

For \cdot_1 , let $\alpha \in D$ and $r \in R$, then

$$\eta(r \cdot_1 \alpha) = (\underline{\partial}(r \cdot_1 \alpha), \Phi(r \cdot_1 \alpha)) = (r \cdot_1 \underline{\partial}\alpha, r \cdot_2 \Phi\alpha)$$

by (3.2.3)(v)

$$= (r \cdot_1 \underline{\partial}\alpha, r \cdot \Phi\alpha) \quad (\text{since } \Phi\alpha \in \mathcal{Y}D)$$

$$= r \cdot_1 (\underline{\partial}\alpha, \Phi\alpha) = r \cdot_1 \eta\alpha . \text{ Similarly for } \cdot_2, \text{ we get}$$

$$\eta(r \cdot_2 \alpha) = r \cdot_2 \eta\alpha .$$

Finally, for the connection Γ, Γ' , let $a \in D_1 = D_2$, so $\Gamma a \in D$ and then $\eta(\Gamma a) = (\underline{\partial}\Gamma a, \Phi\Gamma a) = (\underline{\partial}\Gamma a, 0^2)$ by (3.2.2)(i) $= \Gamma a$. Similarly for Γ' . This is the complete proof of the lemma . □

We continue now to prove the theorem . First, we define $\eta': E \rightarrow D$ to be the identity on E_0 and $E_1 = E_2$ and on E by the formulae :

$$\eta'(\alpha, \zeta) = \left(\begin{array}{c} c \\ 1 \quad d \\ cd \end{array} \right) *_{1} [\Phi\alpha +_{2} \epsilon_{1ab}] *_{1} \left(\begin{array}{c} ab \\ a \quad 1 \\ b \end{array} \right) \text{ as shown below:}$$

$$\begin{array}{c} c \\ 1 \quad t_1 \quad d \\ cd \end{array} *_{1} \left(\begin{array}{c} cd-ab \\ 1 \quad \Phi\alpha \quad 1 \\ 0 \end{array} +_{2} \begin{array}{c} ab \\ 1 \quad \epsilon_{1ab} \quad 1 \\ ab \end{array} \right) *_{1} \begin{array}{c} ab \\ a \quad t_2 \quad 1 \\ b \end{array} ,$$

whenever (α, ζ) has boundary edges of the form $\left(\begin{array}{c} c \\ a \quad d \\ b \end{array} \right)$ and

t_1, t_2 are abbreviations for the thin elements with boundaries

$$\left(\begin{array}{c} c \\ 1 \quad d \\ cd \end{array} \right), \left(\begin{array}{c} ab \\ a \quad 1 \\ b \end{array} \right) .$$

Lemma 3.4.3: The maps η, η' are inverse to each other, that is, (i) $\eta\eta' = 1$ (ii) $\eta'\eta = 1$.

Proof: (i) Let $(\alpha, \zeta) \in E$, with $\partial_1^0 \Phi\alpha = \mu\zeta$ and α has boundary

edges given by $(a \begin{smallmatrix} c \\ b \end{smallmatrix} d)$, then

$$\begin{aligned} \eta\eta'(\alpha, \xi) &= \eta[(1 \begin{smallmatrix} c \\ cd \end{smallmatrix} d) *_{1} (\Phi\alpha +_{2} \epsilon_{1ab}) *_{1} (a \begin{smallmatrix} ab \\ b \end{smallmatrix} 1)] \\ &= \eta(\alpha) = (\underline{\partial}\alpha, \Phi\alpha) . \end{aligned}$$

It is clear that α , $\underline{\partial}\alpha$ has the same boundary $(a \begin{smallmatrix} c \\ b \end{smallmatrix} d)$, and

$$\mu \Phi\alpha = \mu\xi . \text{ Thus } \eta\eta'(\alpha, \xi) = (\alpha, \xi) .$$

(ii) Let $\alpha \in D$, where α has boundary $(a \begin{smallmatrix} c \\ b \end{smallmatrix} d)$, so

$$\eta'\eta(\alpha) = \eta'(\underline{\partial}\alpha, \Phi\alpha) = \alpha \quad (\text{since } \underline{\partial}\alpha, \alpha \text{ have the same boundaries}) . \text{ This is the complete proof of lemma (3.4.3) . } \square$$

This completes the proof that $\eta: D \dashrightarrow E$ is an isomorphism . The naturality of η is clear . So we have proved the natural equivalence $1 \cong \lambda\gamma$. \square

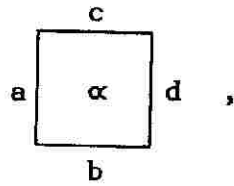
We move on to give a property of these objects by using the above theorem .

5. REFLECTION:

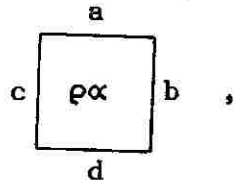
In this section we use the above theorem to show that every object in $\underline{DA}^!$ has a nice property called "reflection" : in a special double algebroid with connection the two algebroid structures are isomorphic .

This property has been given in the double groupoid case in [B-2] under the name "rotation" . Reflections in double categories with connection have also studied in [S-1],[S-W-] .

For each object $(D, \Gamma, \Gamma') \in \underline{DA}^!$, there is a reflection $\rho : D \dashrightarrow D$ such that on edges ρ behaves as follows : let α be a square in D , pictured as

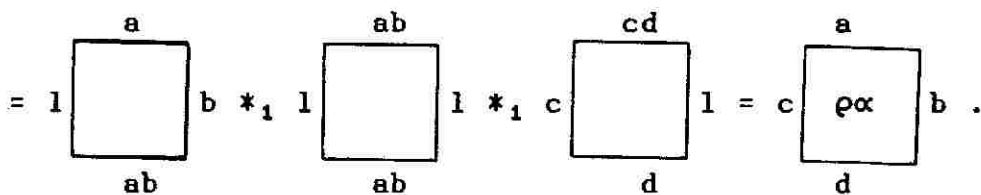
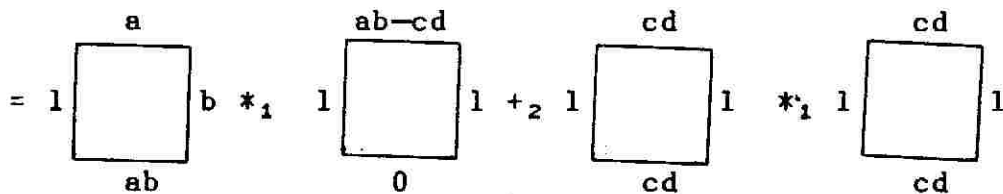
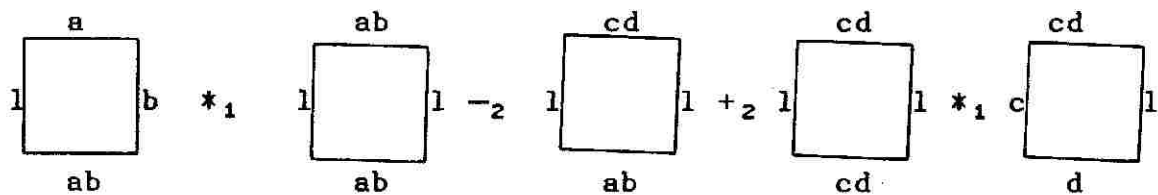
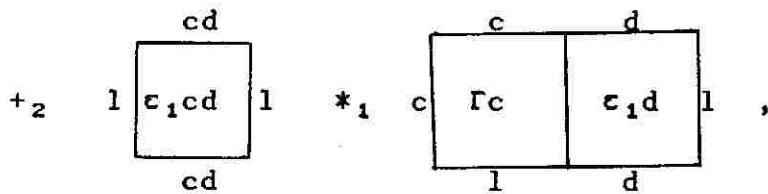
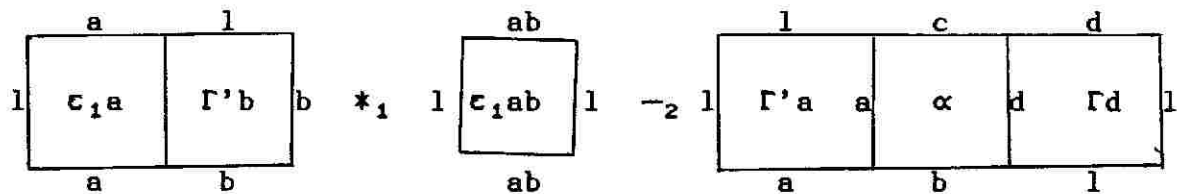


then $\rho\alpha$ is a square in the form



and $\rho\alpha$ is defined by

$$\rho\alpha = (\epsilon_1 a *_2 \Gamma' b) *_1 [(\epsilon_1 ab -_2 (\Gamma' a *_2 \alpha *_2 \Gamma d)) +_2 \epsilon_1 cd] *_1 (\Gamma c *_2 \epsilon_1 d), \text{ as shown diagrammatically ;}$$



Theorem 3.5.1: The reflection ρ satisfies

i) $\rho(\Gamma a) = \Gamma a$, $\rho(\Gamma' a) = \Gamma' a$, $\rho(\epsilon_1 a) = \epsilon_1 a$, $\rho(\epsilon_2 a) = \epsilon_2 a$,
for $a \in D_2$ or D_1 .

ii) $\rho(\alpha +_1 \beta) = \rho\alpha +_2 \rho\beta$, $\rho(\gamma +_2 \delta) = \rho\gamma +_1 \rho\delta$, whenever
 $\alpha +_1 \beta$, $\gamma +_2 \delta$ are defined .

iii) $\rho(\alpha *_1 \beta) = \rho\alpha *_2 \rho\beta$, $\rho(\gamma *_2 \delta) = \rho\gamma *_1 \rho\delta$, whenever
 $\alpha *_1 \beta$, $\gamma *_2 \delta$ are defined .

iv) $\rho^2 = \text{id}$.

v) $\rho(r \cdot_1 \alpha) = r \cdot_2 \rho\alpha$, $\rho(r \cdot_2 \alpha) = r \cdot_1 \rho\alpha$, where $r \in R$.

Proof: By theorem (3.4.1) , we may assume that D is the double
algebroid arising from a crossed module $\mu: M \rightarrow A$. So if

$\alpha \in D$, we may write $\alpha = (m; \begin{smallmatrix} a & c \\ ab & d \end{smallmatrix})$, where $m \in M$,

$a, b, c, d \in A$ and $\mu m = cd - ab$. We calculate now $\rho(\alpha)$ as
follows :

$$\begin{aligned} \rho(\alpha) &= (0; \begin{smallmatrix} a & \\ ab & b \end{smallmatrix}) *_1 [((0; \begin{smallmatrix} ab & \\ ab & 1 \end{smallmatrix}) -_2 (m; \begin{smallmatrix} cd & \\ ab & 1 \end{smallmatrix})) +_2 \\ & (0; \begin{smallmatrix} cd & \\ cd & 1 \end{smallmatrix})] *_1 (0; \begin{smallmatrix} cd & \\ c & d \end{smallmatrix}) \\ &= (0; \begin{smallmatrix} a & \\ ab & b \end{smallmatrix}) *_1 [((0; \begin{smallmatrix} ab & \\ ab & 1 \end{smallmatrix}) +_2 (-m; \begin{smallmatrix} -cd & \\ -ab & 1 \end{smallmatrix})) +_2 (0; \begin{smallmatrix} cd & \\ cd & 1 \end{smallmatrix})] \\ & *_1 (0; \begin{smallmatrix} cd & \\ c & d \end{smallmatrix}) \\ &= (0; \begin{smallmatrix} a & \\ ab & b \end{smallmatrix}) *_1 (-m; \begin{smallmatrix} ab & \\ cd & 1 \end{smallmatrix}) *_1 (0; \begin{smallmatrix} cd & \\ c & d \end{smallmatrix}) = (-m; \begin{smallmatrix} a & \\ c & d \end{smallmatrix}) *_1 (0; \begin{smallmatrix} a & \\ ab & b \end{smallmatrix}) . \end{aligned}$$

Now we verify the relations (i-v) .

i) $\rho(\Gamma a) = \rho(0; \begin{smallmatrix} a & \\ a & 1 \end{smallmatrix}) = (0; \begin{smallmatrix} a & \\ a & 1 \end{smallmatrix}) = \Gamma a$ and by similar way for

$\Gamma' a$, $\epsilon_1 a$, $\epsilon_2 a$.

ii) Let $\alpha, \beta \in D$ with boundaries $(a \begin{smallmatrix} c \\ b \end{smallmatrix} d)$, $(a_1 \begin{smallmatrix} c \\ b \end{smallmatrix} d_1)$, then

$$\rho(\alpha +_1 \beta) = (-(m+m_1); c \begin{smallmatrix} a+a_1 \\ d+d_1 \end{smallmatrix} b) . \text{ On the other hand ;}$$

$$\rho(\alpha) +_2 \rho(\beta) = (-m; c \begin{smallmatrix} a \\ d \end{smallmatrix} b) +_2 (-m_1; c \begin{smallmatrix} a_1 \\ d_1 \end{smallmatrix} b) = (-(m+m_1); c \begin{smallmatrix} a+a_1 \\ d+d_1 \end{smallmatrix} b)$$

= $\rho(\alpha +_1 \beta)$. Thus $\rho(\alpha +_1 \beta) = \rho\alpha +_2 \rho\beta$. Also we prove similarly that $\rho(\gamma +_2 \delta) = \rho\gamma +_1 \rho\delta$.

iii) Let $\alpha, \beta \in D$ with boundaries $(a \begin{smallmatrix} c \\ b \end{smallmatrix} d)$, $(a' \begin{smallmatrix} b \\ e \end{smallmatrix} d')$, then

$$\rho(\alpha *_1 \beta) = (-(mm'); c \begin{smallmatrix} aa' \\ dd' \end{smallmatrix} e) . \text{ On the other hand ;}$$

$$\rho(\alpha) *_2 \rho(\beta) = (-m; c \begin{smallmatrix} a \\ d \end{smallmatrix} b) *_2 (-m'; b \begin{smallmatrix} a' \\ d' \end{smallmatrix} e) = (-(mm'); c \begin{smallmatrix} aa' \\ dd' \end{smallmatrix} e) .$$

Thus $\rho(\alpha *_1 \beta) = \rho\alpha *_2 \rho\beta$. Similarly for $\rho(\gamma *_2 \delta) = \rho\gamma *_1 \rho\delta$.

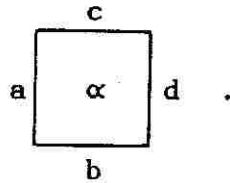
The calculation of (iv), (v) are easy to verify . Therefore ρ satisfies the relations (i-v) . \square

APPENDIX I

Verification of Theorem (3.1.7) and Lemma (3.1.8):

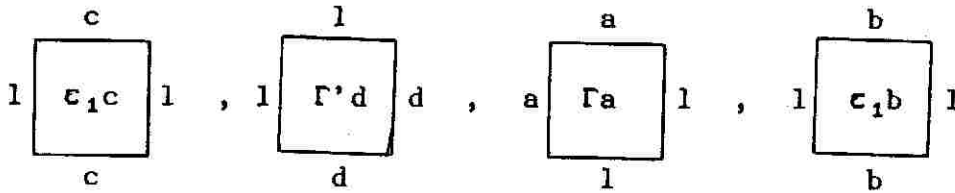
i) The definition of θ_1, θ_2 :

Let $a, b, c, d \in D_1$ with $cd = ab$ and α has boundary given by

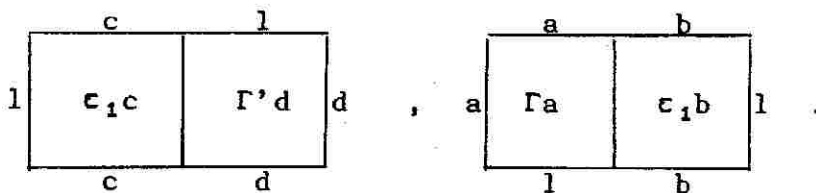


Since $\theta_1(a \begin{smallmatrix} c \\ b \end{smallmatrix} d) = (\epsilon_1 c *_2 \Gamma' d) *_1 (\Gamma a *_2 \epsilon_1 b)$ and $\epsilon_1 c, \Gamma' d,$

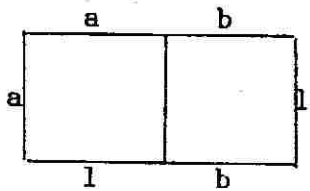
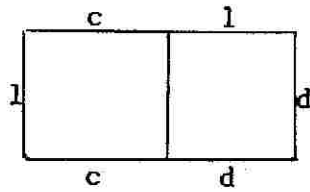
$\Gamma a, \epsilon_1 b$ have boundaries given by



and then $(\epsilon_1 c *_2 \Gamma' d), (\Gamma a *_2 \epsilon_1 b)$ have boundaries in the form



Thus $(\epsilon_1 c *_2 \Gamma' d) *_1 (\Gamma a *_2 \epsilon_1 b)$ is defined (since $cd = ab$) ;
namely

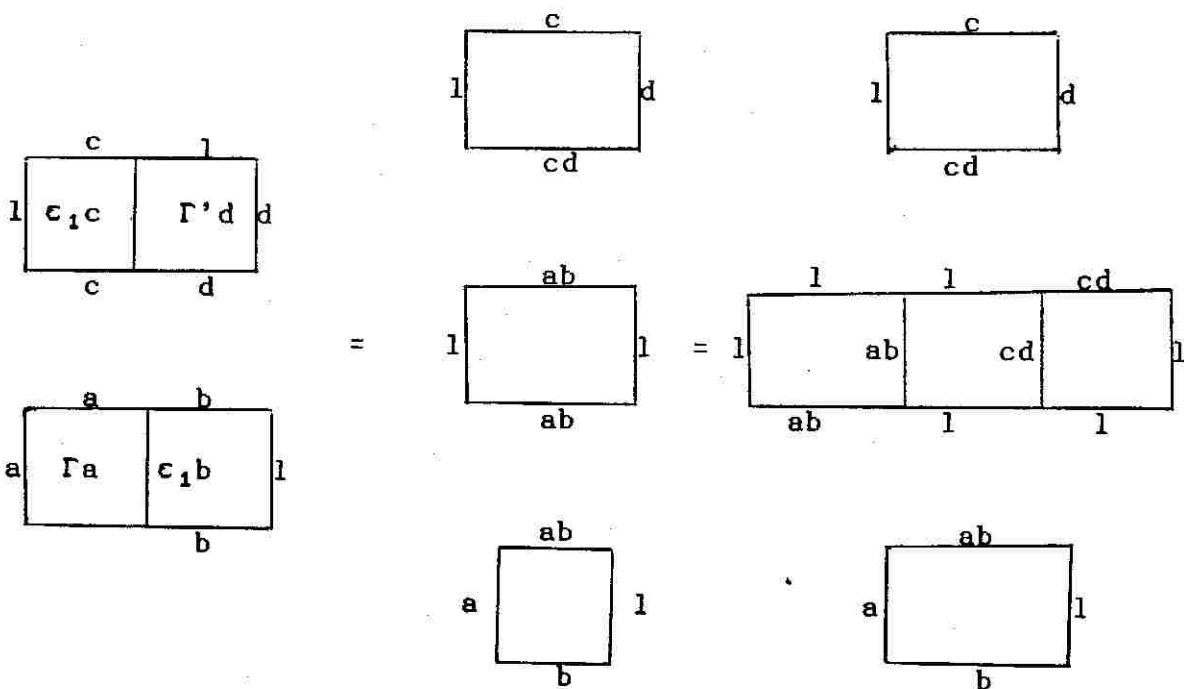


Similarly for the definition of θ_2 .

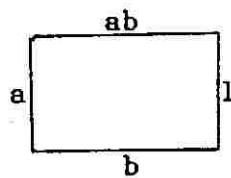
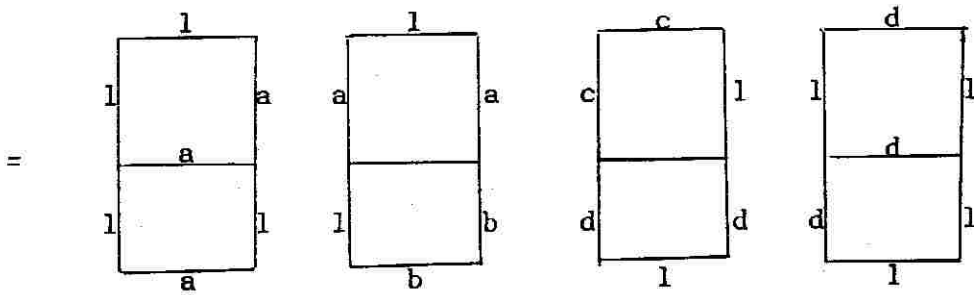
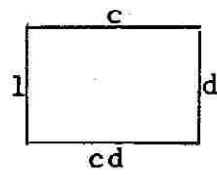
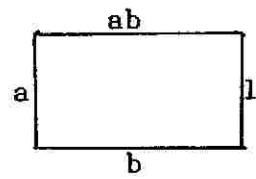
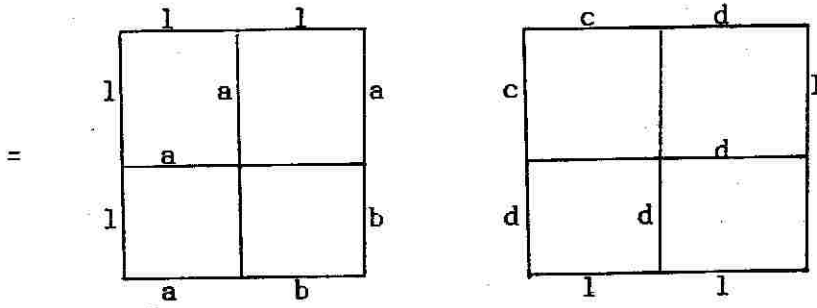
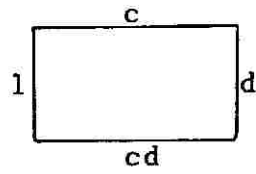
ii) Lemma 3.1.8:

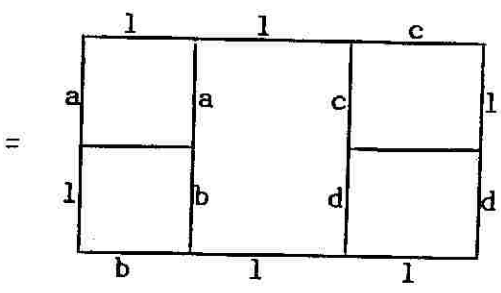
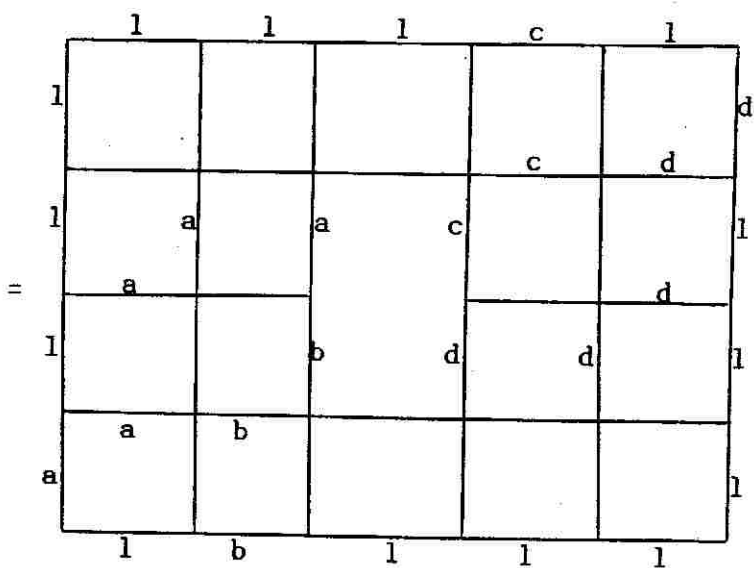
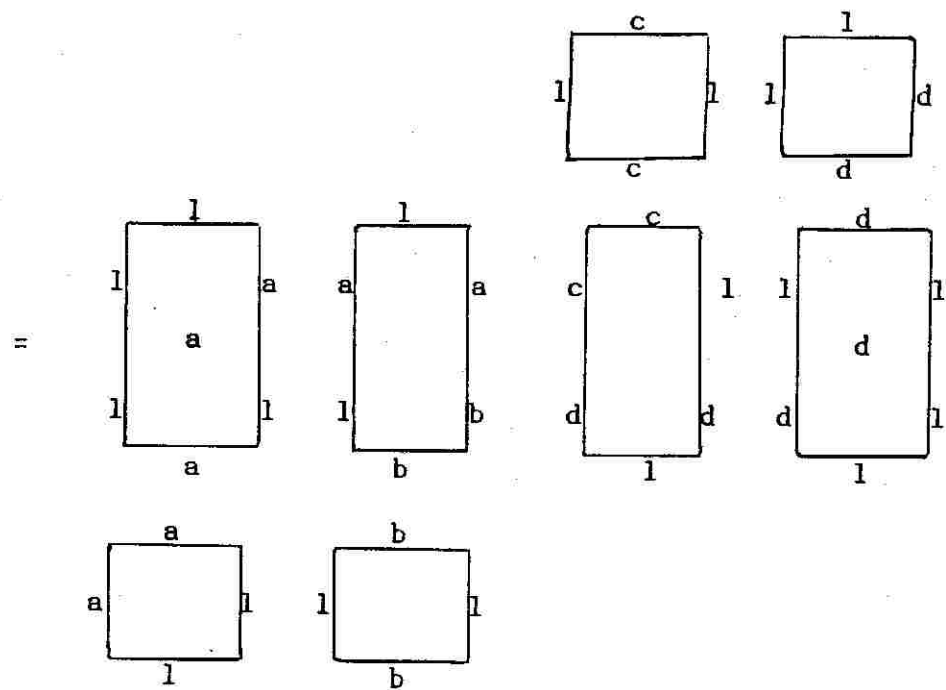
$$e_1 \begin{pmatrix} c \\ a & d \\ b \end{pmatrix} = (e_1 c *_2 \Gamma' d) *_1 (\Gamma a *_2 e_1 b) \text{ which is}$$

diagrammatically given by



(since $cd = ab$),



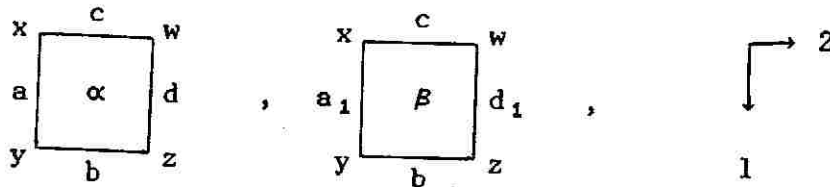


$$= (\epsilon_2 a *_{1} \Gamma' b) *_{2} (\Gamma c *_{1} \epsilon_2 d) .$$

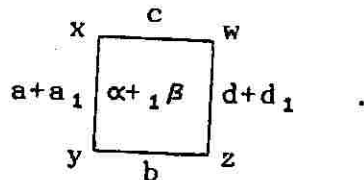
APPENDIX II

Verification of proposition (3.2.3) diagrammatically:

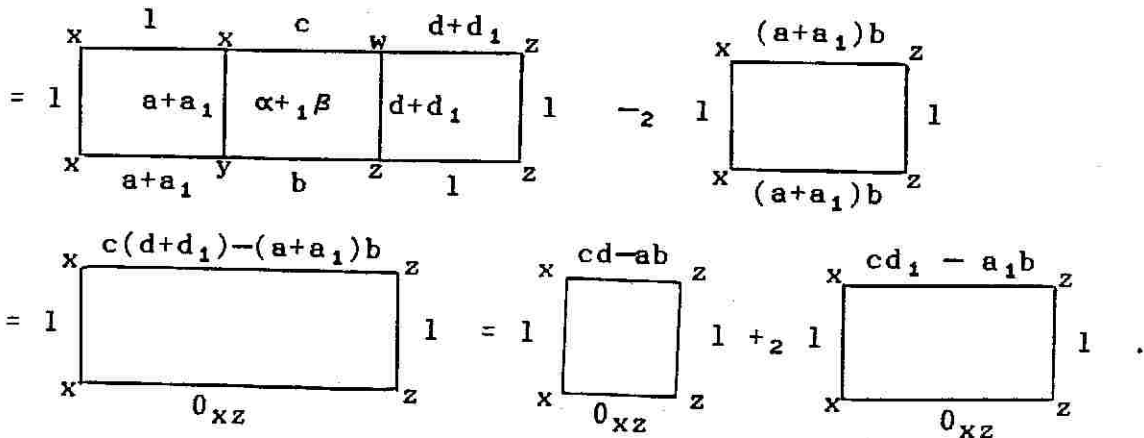
i) Let $\alpha, \beta \in D$ be given by



thus $\alpha +_1 \beta$ is in the form

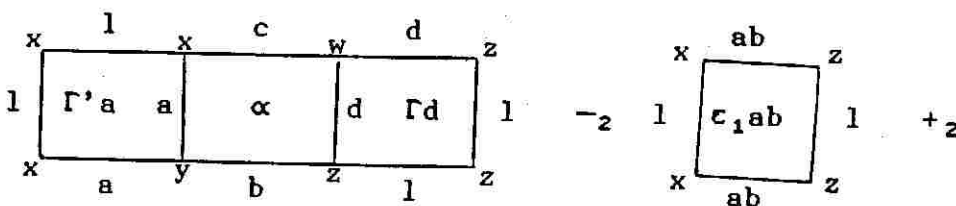


$$\Phi(\alpha +_1 \beta) = [\Gamma'(a+a_1) *_2 (\alpha +_1 \beta) *_2 \Gamma(d+d_1)] -_2 \epsilon_1(a+a_1)b ,$$



On the other hand ;

$$\Phi\alpha +_2 \Phi\beta = [(\Gamma'a *_2 \alpha *_2 \Gamma d) -_2 \epsilon_1 ab] +_2 [(\Gamma'a_1 *_2 \beta *_2 \Gamma d_1) -_2 \epsilon_1 a_1 b] , \text{ is in the form}$$

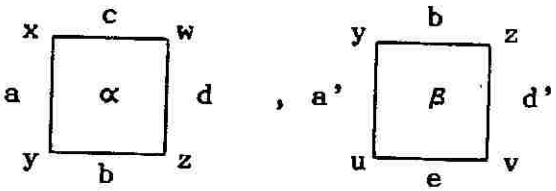


$$\begin{array}{c}
 \begin{array}{c}
 \begin{array}{ccccccc}
 & l & & c & & w & d_1 \\
 x & & x & & & & z \\
 l & \Gamma' a_1 & a_1 & & \beta & & d_1 \Gamma d_1 \\
 & & & & & & & l \\
 x & & y & & b & & z & & z \\
 & a_1 & & & & & l & &
 \end{array} \\
 -_2 \quad \begin{array}{c}
 \begin{array}{ccc}
 x & a_1 b & z \\
 l & c_1 a_1 b & l \\
 x & a_1 b & z
 \end{array}
 \end{array} \\
 \\
 = \begin{array}{c}
 \begin{array}{c}
 \begin{array}{ccc}
 x & cd-ab & z \\
 l & & l \\
 x & 0_{xz} & z
 \end{array} \\
 +_2 \quad \begin{array}{c}
 \begin{array}{ccc}
 x & cd_1 - a_1 b & z \\
 l & & l \\
 x & 0_{xz} & z
 \end{array}
 \end{array}
 \end{array}
 \end{array}$$

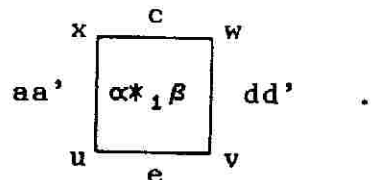
ii) Similarly for $\Phi(\alpha +_2 \beta) = \Phi\alpha +_2 \Phi\beta$.

iii) For $\Phi(\alpha *_1 \beta) = (\Phi\alpha *_2 \epsilon_1 \partial_2^1 \beta) +_2 (\epsilon_1 \partial_1^0 \alpha *_2 \Phi\beta)$.

Let α, β be given by

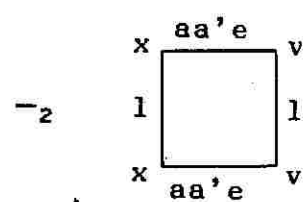
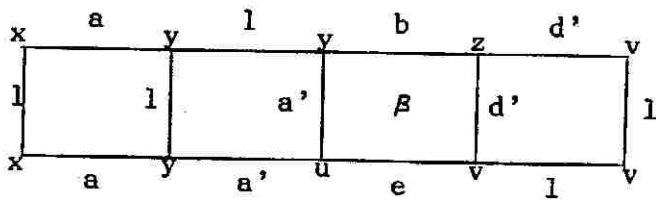
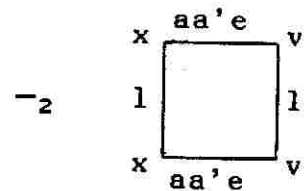
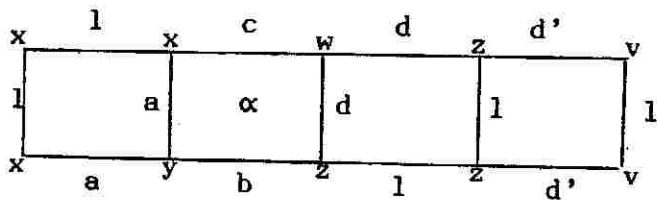
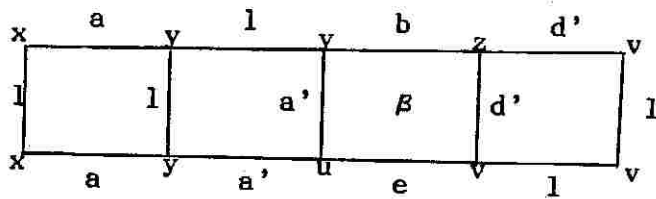
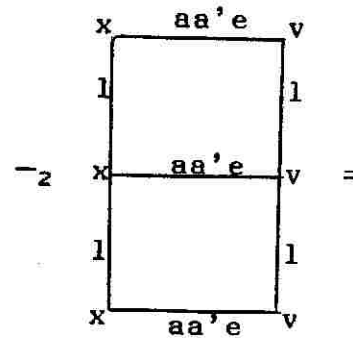
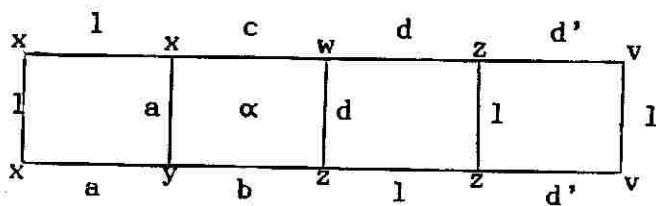
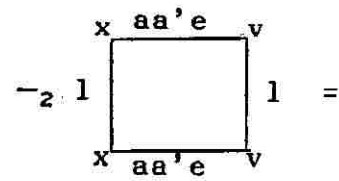
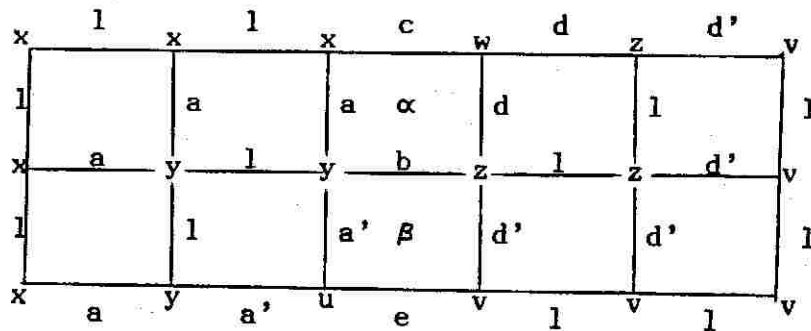


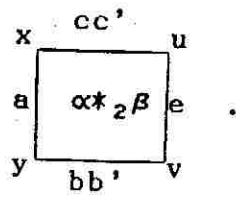
and so $\alpha *_1 \beta$ is in the form



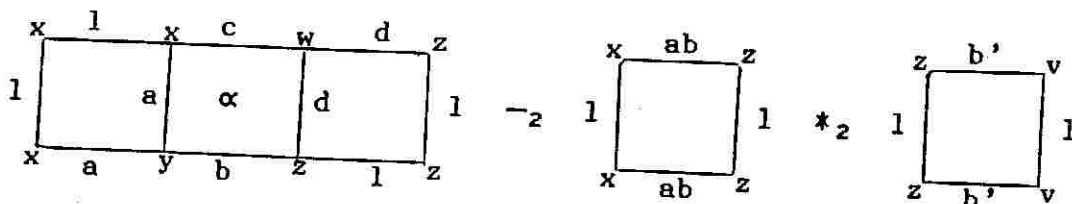
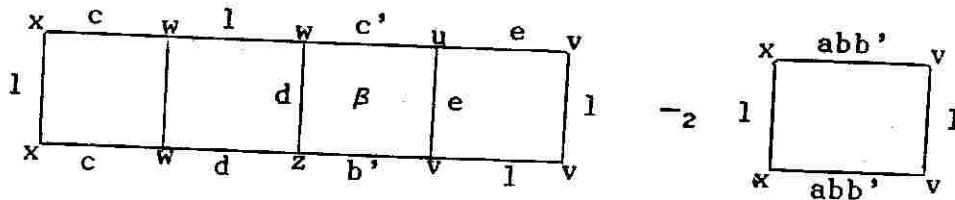
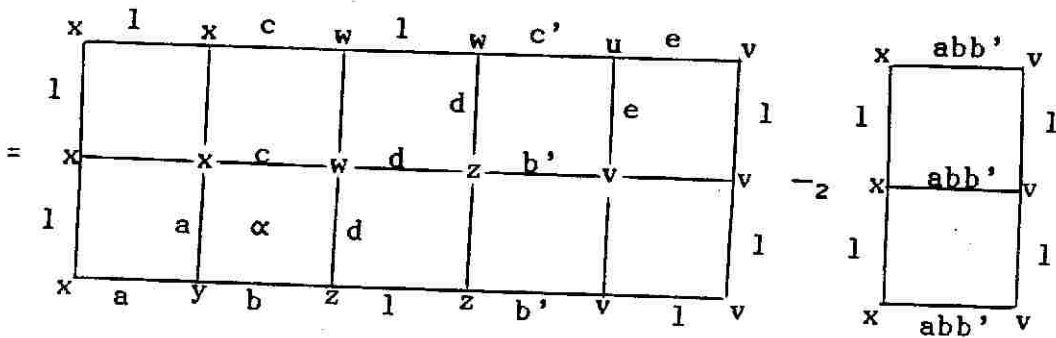
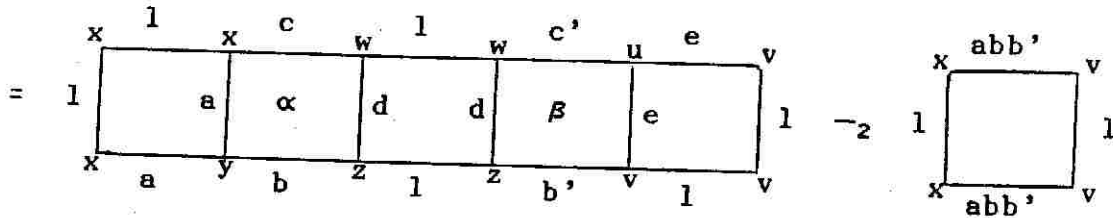
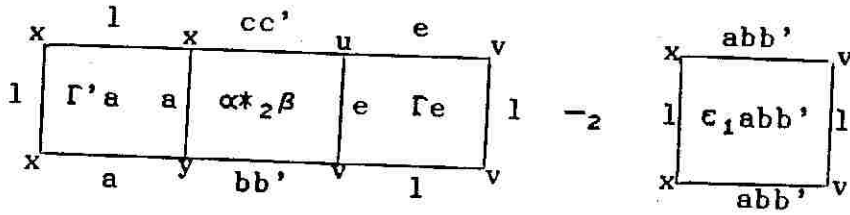
Now $\Phi(\alpha *_1 \beta) = (\Gamma' aa' *_2 (\alpha *_1 \beta) *_2 \Gamma dd')$ $-_2 \epsilon_1 aa'e$, which is diagrammatically pictured as

$$\begin{array}{c}
 \begin{array}{c}
 \begin{array}{ccccccc}
 & l & & c & & w & dd' \\
 x & & x & & & & v \\
 l & aa' & & & & & dd' \\
 & & & & & & & l \\
 x & & u & & e & & v & & v \\
 & aa' & & & & & l & &
 \end{array} \\
 -_2 \quad \begin{array}{c}
 \begin{array}{ccc}
 x & aa'e & v \\
 l & & l \\
 x & aa'e & v
 \end{array}
 \end{array} =
 \end{array}$$





Then $\Phi(\alpha * 2 \beta) = (\Gamma'a * 2 (\alpha * 2 \beta) * 2 \Gamma d) \rightarrow_2 \epsilon_1 abb'$ which is in the form



$$\left[\begin{array}{c} \begin{array}{|c|c|c|} \hline x & c & w \\ \hline 1 & & 1 \\ \hline x & c & w \\ \hline \end{array} *_2 \left(\begin{array}{|c|c|c|c|} \hline w & 1 & w & c' & u & e & v \\ \hline 1 & & d & \beta & & e & 1 \\ \hline w & d & z & b' & v & & 1 \\ \hline \end{array} -_2 \begin{array}{|c|c|} \hline w & db' & v \\ \hline 1 & & 1 \\ \hline w & & v \\ \hline \end{array} \right) +_2 \begin{array}{|c|c|c|} \hline x & cdb' & -abb' & v \\ \hline 1 & & & 1 \\ \hline x & cdb' & -abb' & v \\ \hline \end{array} \right]$$

=

$$\begin{array}{|c|c|c|} \hline x & 0 & v \\ \hline 1 & \epsilon_1 0 & 1 \\ \hline x & 0 & v \\ \hline \end{array} +_2 \left(\begin{array}{|c|c|c|} \hline x & cd-ab & z \\ \hline 1 & \Phi\alpha & 1 \\ \hline x & 0 & z \\ \hline \end{array} *_2 \begin{array}{|c|c|} \hline z & b' & v \\ \hline 1 & & 1 \\ \hline z & b' & v \\ \hline \end{array} \right)$$

$$\left(\begin{array}{|c|c|c|} \hline x & c & w \\ \hline 1 & & 1 \\ \hline x & c & w \\ \hline \end{array} *_2 \begin{array}{|c|c|c|} \hline w & c'e-db' & v \\ \hline 1 & \Phi\beta & 1 \\ \hline w & 0 & v \\ \hline \end{array} \right) +_2 \begin{array}{|c|c|c|} \hline x & cdb' & -abb' & v \\ \hline 1 & & & 1 \\ \hline x & cdb' & -abb' & v \\ \hline \end{array}$$

=

$$\begin{array}{|c|c|c|} \hline x & 0 & v \\ \hline 1 & \epsilon_1 0 & 1 \\ \hline x & 0 & v \\ \hline \end{array} +_2 \left(\begin{array}{|c|c|c|} \hline x & cd-ab & z \\ \hline 1 & \Phi\alpha & 1 \\ \hline x & 0 & z \\ \hline \end{array} *_2 \begin{array}{|c|c|} \hline z & b' & v \\ \hline 1 & & 1 \\ \hline z & b' & v \\ \hline \end{array} \right)$$

$$= \left(\begin{array}{|c|c|c|} \hline x & c & w \\ \hline 1 & & 1 \\ \hline x & c & w \\ \hline \end{array} *_2 \begin{array}{|c|c|c|} \hline w & c'e-db' & v \\ \hline 1 & \Phi\beta & 1 \\ \hline w & 0 & v \\ \hline \end{array} \right) +_2 \left(\begin{array}{|c|c|c|} \hline x & cd-ab & z \\ \hline 1 & \Phi\alpha & 1 \\ \hline x & 0 & z \\ \hline \end{array} *_2 \begin{array}{|c|c|} \hline z & b' & v \\ \hline 1 & & 1 \\ \hline z & b' & v \\ \hline \end{array} \right)$$

$$= (\epsilon_1 c *_2 \Phi\beta) +_2 (\Phi\alpha *_2 \epsilon_1 b')$$

v) The rules $\Phi(r \cdot_1 \alpha) = r \cdot_2 \Phi\alpha$ and $\Phi(r \cdot_2 \alpha) = r \cdot_2 \Phi\alpha$ are clear.